

Analysis of Algorithms

CS 477/677

Instructor: Monica Nicolescu

Lecture 15

Dynamic Programming

- An algorithm design technique used for **optimization problems**
 - Find a solution with the **optimal value** (minimum or maximum)
 - A set of **choices** must be made to get an optimal solution
 - There may be multiple solutions that return the optimal value: we want to find one of them

Dynamic Programming

- Similar to divide and conquer, but with one key difference
 - Subproblems are **not independent**: **subproblems share subsubproblems**
- Divide and conquer
 - Partition the problem into **independent** subproblems
 - Solve the subproblems recursively
 - Combine the solutions to solve the original problem

Dynamic Programming

- Applicable when subproblems are **not independent**
 - Subproblems share subsubproblems

E.g.: Fibonacci numbers:

- Recurrence: $F(n) = F(n-1) + F(n-2)$
- Boundary conditions: $F(1) = 0, F(2) = 1$
- Compute: $F(5) = 3, F(3) = 1, F(4) = 2$
- A divide and conquer approach would repeatedly solve the common subproblems
- Dynamic programming solves every subproblem just once and stores the answer in a table

Dynamic Programming Algorithm

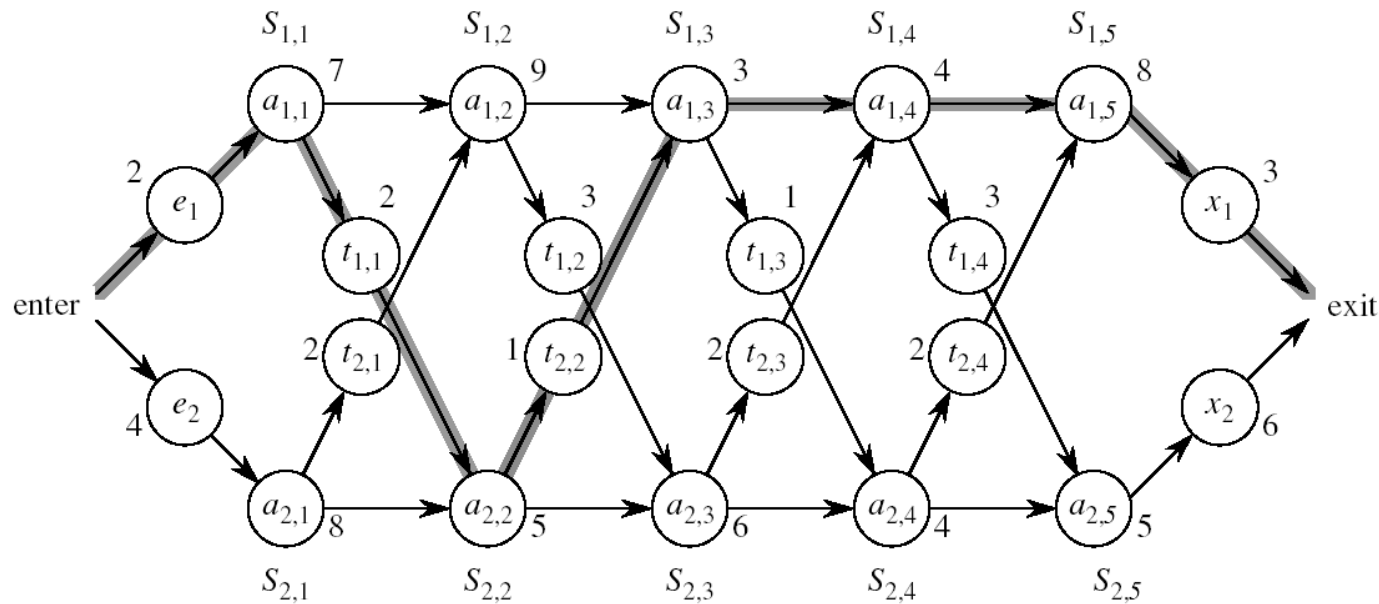
1. Characterize the structure of an optimal solution
2. Recursively define the value of an optimal solution
3. Compute the value of an optimal solution in a bottom-up fashion
4. Construct an optimal solution from computed information

Elements of Dynamic Programming

- Optimal Substructure
 - An optimal solution to a problem contains within it an optimal solution to subproblems
 - Optimal solution to the entire problem is built in a bottom-up manner from optimal solutions to subproblems
- Overlapping Subproblems
 - If a recursive algorithm revisits the same subproblems again and again \Rightarrow the problem has overlapping subproblems

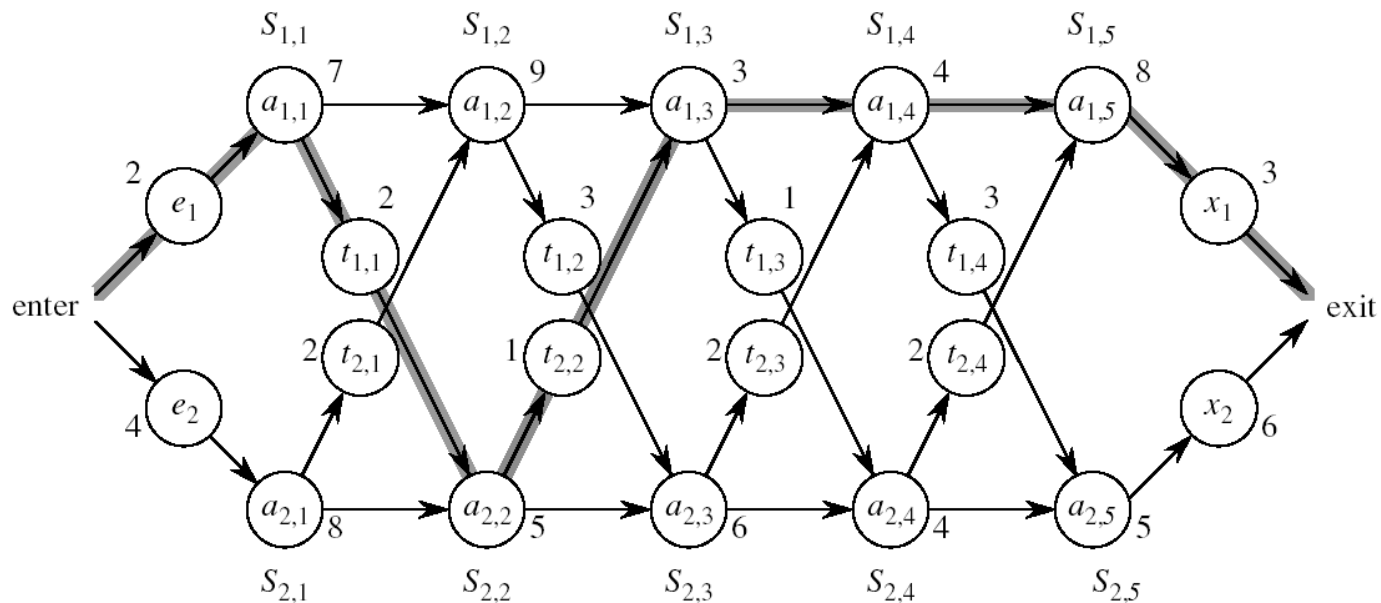
Assembly Line Scheduling

- Automobile factory with two assembly lines
 - Each line has n stations: $S_{1,1}, \dots, S_{1,n}$ and $S_{2,1}, \dots, S_{2,n}$
 - Corresponding stations $S_{1,j}$ and $S_{2,j}$ perform the same function but can take different amounts of time $a_{1,j}$ and $a_{2,j}$
 - Times to enter are e_1 and e_2 and times to exit are x_1 and x_2



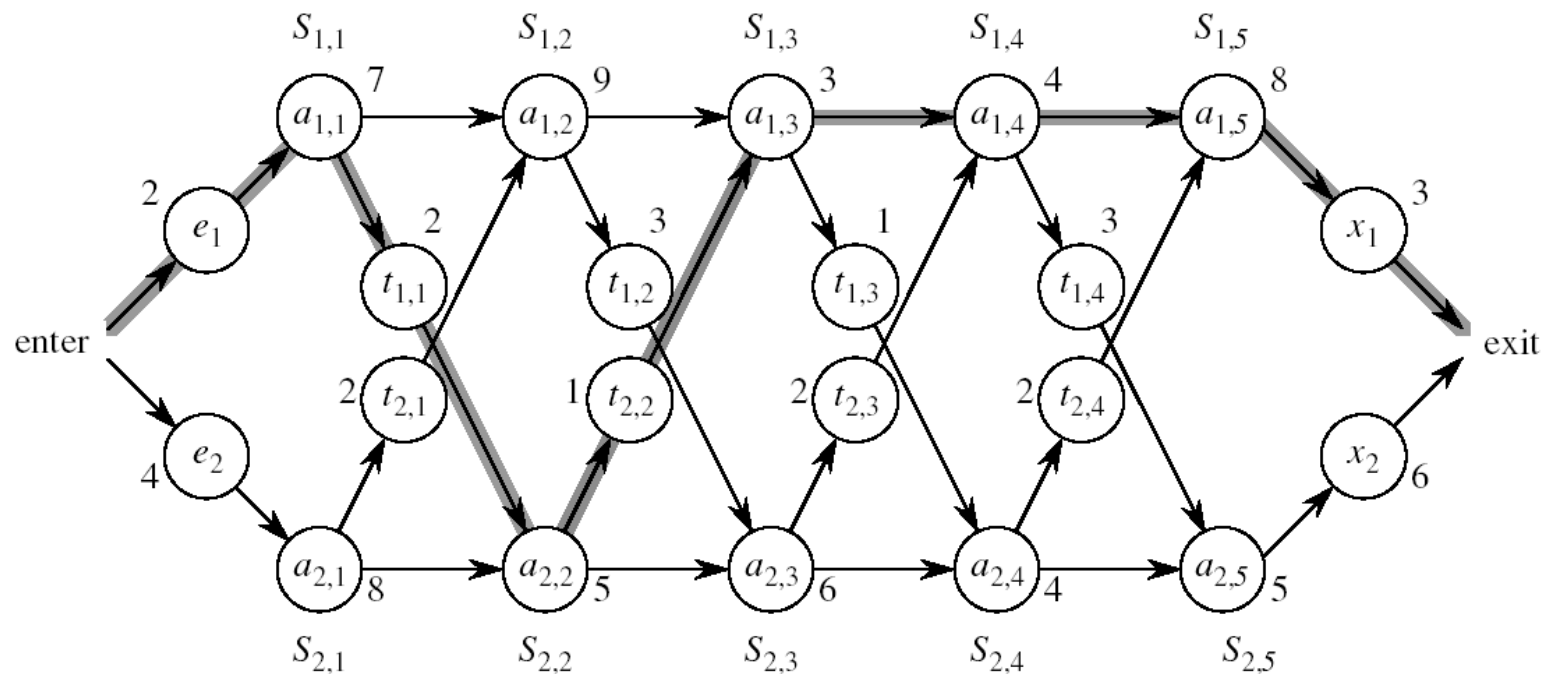
Assembly Line

- After going through a station, the car can either:
 - stay on same line at no cost, or
 - transfer to other line: cost after $S_{i,j}$ is $t_{i,j}$, $i = 1, 2, j = 1, \dots, n-1$



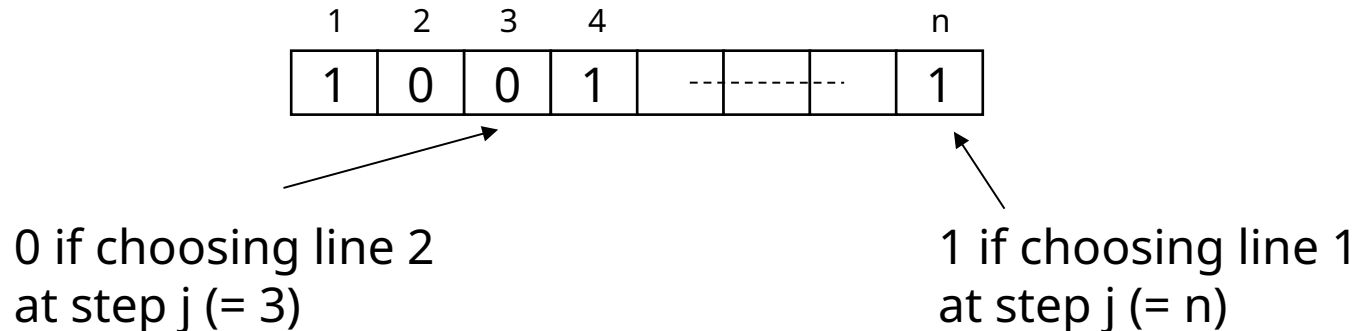
Assembly Line Scheduling

- Problem:
What stations should be chosen from line 1 and what from line 2 in order to **minimize the total time through the factory for one car?**



One Solution

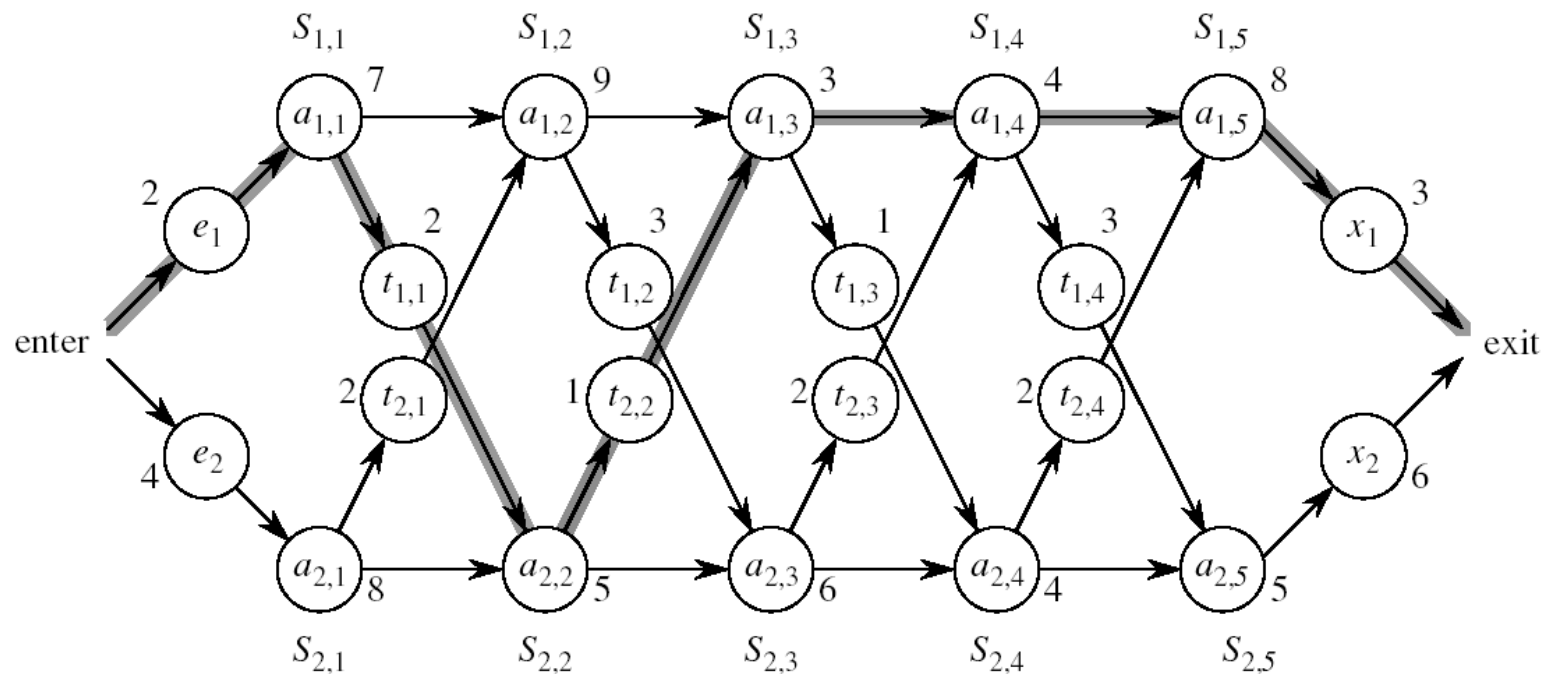
- Brute force
 - Enumerate all possibilities of selecting stations
 - Compute how long it takes in each case and choose the best one



- There are 2^n possible ways to choose stations
- Infeasible when n is large

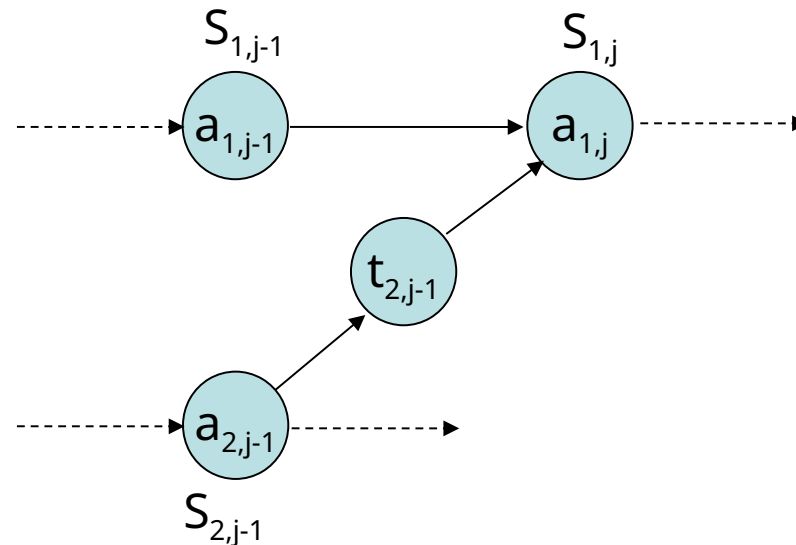
1. Structure of the Optimal Solution

- How do we compute the minimum time of going through the station?



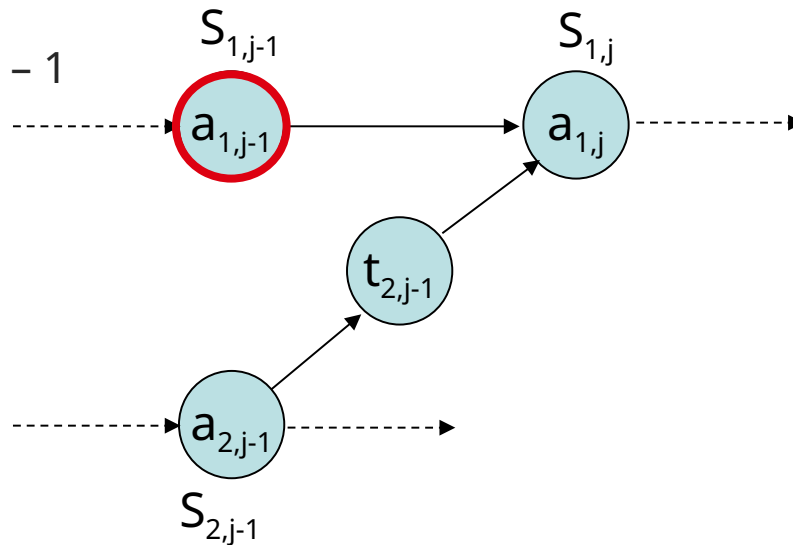
1. Structure of the Optimal Solution

- Let's consider all possible ways to get from the starting point through station $S_{1,j}$
 - We have two choices of how to get to $S_{1,j}$:
 - Through $S_{1,j-1}$, then directly to $S_{1,j}$
 - Through $S_{2,j-1}$, then transfer over to $S_{1,j}$



1. Structure of the Optimal Solution

- Suppose that **the fastest way through $S_{1,j}$ is through $S_{1,j-1}$**
 - We must have taken the fastest way from entry through $S_{1,j-1}$
 - If there were a faster way through $S_{1,j-1}$, we would use it instead
- Similarly for $S_{2,j-1}$

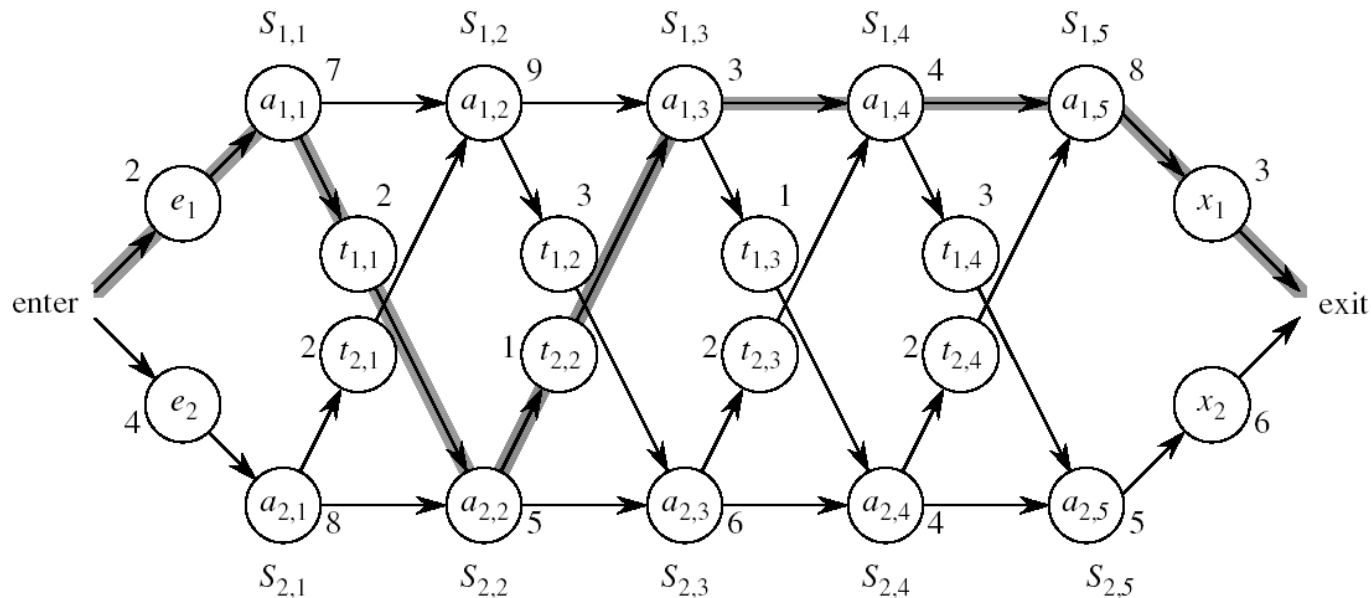


Optimal Substructure

- **Generalization:** an optimal solution to the problem **find the fastest way through $S_{1,j}$** contains within it an optimal solution to subproblems: **find the fastest way through $S_{1,j-1}$ or $S_{2,j-1}$** .
- This is referred to as the **optimal substructure** property
- We use this property to construct an optimal solution to a problem from optimal solutions to subproblems

2. A Recursive Solution

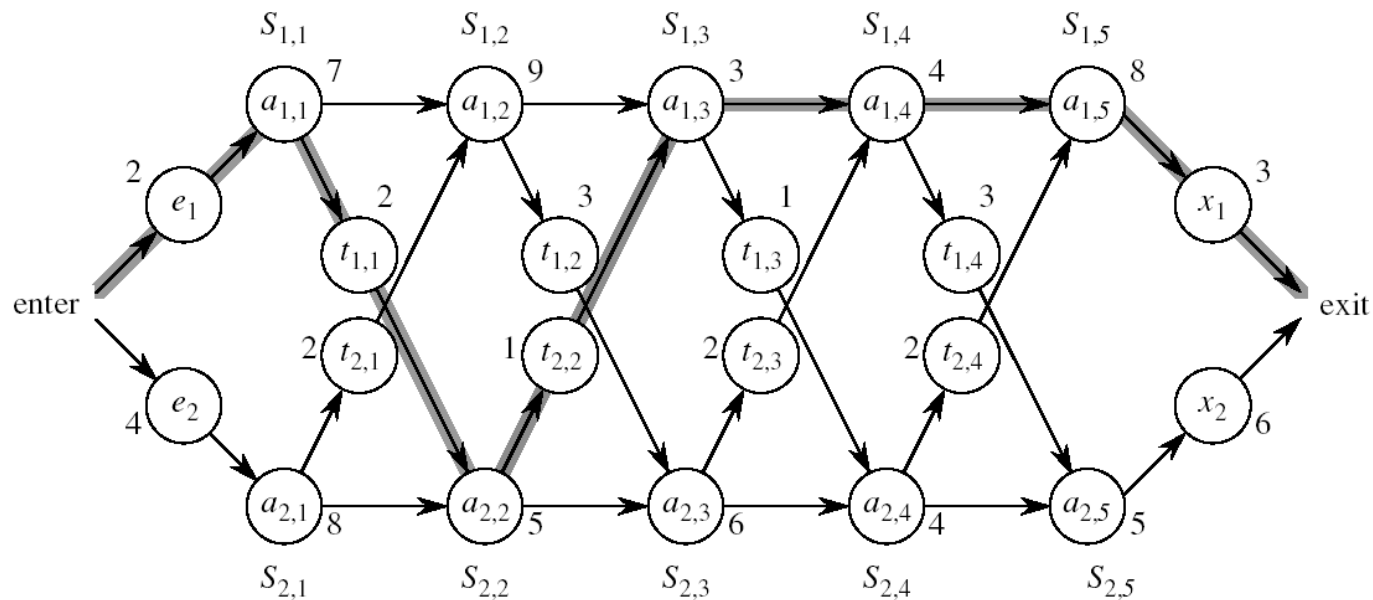
- Define the value of an optimal solution in terms of the optimal solution to subproblems
- Assembly line subproblems
 - Finding the fastest way through each station j on each line i ($i = 1, 2, j = 1, 2, \dots, n$)



2. A Recursive Solution

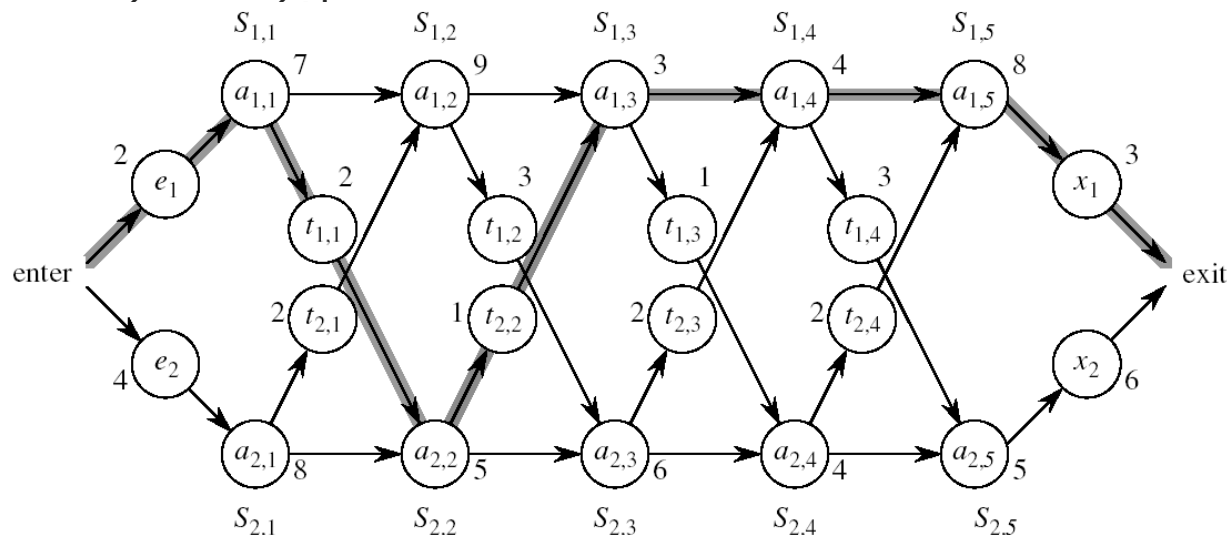
- f^* = the fastest time to get through the entire factory
- $f_i[j]$ = the fastest time to get from the starting point through station $S_{i,j}$

$$f^* = \min(f_1[n] + x_1, f_2[n] + x_2)$$



2. A Recursive Solution

- $f_i[j]$ = the fastest time to get from the starting point through station $S_{i,j}$
- $j = 1$ (getting through station 1)
 $f_1[1] = e_1 + a_{1,1}$
 $f_2[1] = e_2 + a_{2,1}$



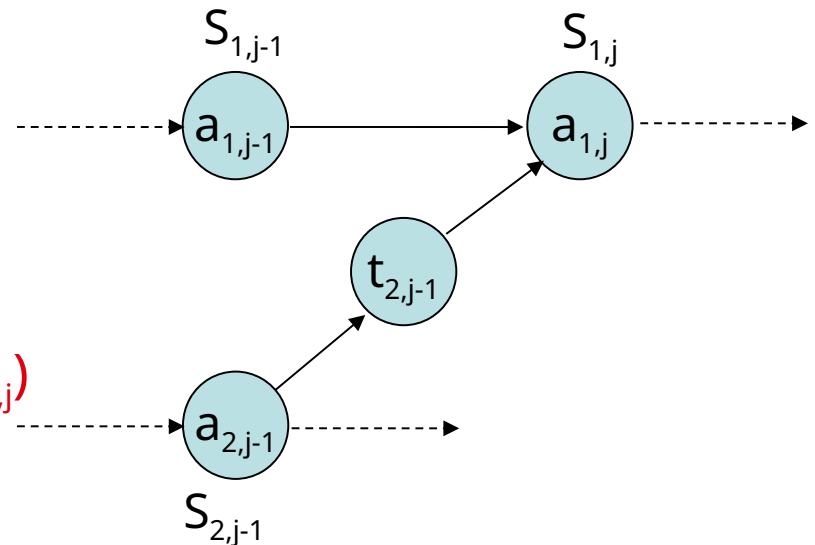
2. A Recursive Solution

- Compute $f_i[j]$ for $j = 2, 3, \dots, n$, and $i = 1, 2$
- Fastest way through $S_{1,j}$ is either:
 - the way through $S_{1,j-1}$ then directly through $S_{1,j}$, or
 - the way through $S_{2,j-1}$, transfer from line 2 to line 1, then through $S_{1,j}$

$$f_1[j-1] + a_{1,j}$$

$$f_2[j-1] + t_{2,j-1} + a_{1,j}$$

$$f_1[j] = \min(f_1[j-1] + a_{1,j}, f_2[j-1] + t_{2,j-1} + a_{1,j})$$



2. A Recursive Solution

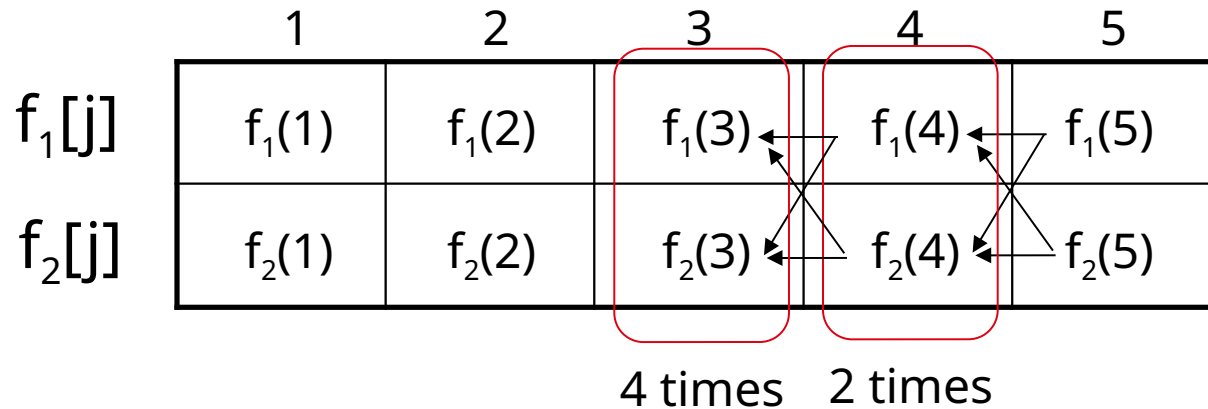
$$f_1[j] = \begin{cases} e_1 + a_{1,1} & \text{if } j = 1 \\ \min(f_1[j-1] + a_{1,j}, f_2[j-1] + t_{2,j-1} + a_{1,j}) & \text{if } j \geq 2 \end{cases}$$

$$f_2[j] = \begin{cases} e_2 + a_{2,1} & \text{if } j = 1 \\ \min(f_2[j-1] + a_{2,j}, f_1[j-1] + t_{1,j-1} + a_{2,j}) & \text{if } j \geq 2 \end{cases}$$

3. Computing the Optimal Value

$$f^* = \min (f_1[n] + x_1, f_2[n] + x_2)$$

$$f_1[j] = \min(f_1[j-1] + a_{1,j}, f_2[j-1] + t_{2,j-1} + a_{1,j})$$



- Solving top-down would result in exponential running time

3. Computing the Optimal Value

- For $j \geq 2$, each value $f_i[j]$ depends only on the values of $f_1[j - 1]$ and $f_2[j - 1]$
- Compute the values of $f_i[j]$
 - in increasing order of j


Diagram illustrating the increasing order of j (indicated by a red arrow) for the computation of $f_1[j]$ and $f_2[j]$ across $j = 1$ to $j = 5$.

	1	2	3	4	5
$f_1[j]$					
$f_2[j]$					

- Bottom-up approach
 - First find optimal solutions to subproblems
 - Find an optimal solution to the problem from the subproblems

4. Construct the Optimal Solution

- We need the information about which line has been used at each station:
 - $I_i[j]$ – the line number (1, 2) whose station $(j - 1)$ has been used to get in fastest time through $S_{i,j}$, $j = 2, 3, \dots, n$
 - I^* – the line number (1, 2) whose station n has been used to get in fastest time through the exit point
- increasing j



	2	3	4	5
$I_1[j]$				
$I_2[j]$				

FASTEST-WAY(a, t, e, x, n)

```

1.  $f_1[1] \leftarrow e_1 + a_{1,1}$ 
2.  $f_2[1] \leftarrow e_2 + a_{2,1}$ 
    } Compute initial values of  $f_1$  and  $f_2$ 

3. for  $j \leftarrow 2$  to  $n$ 
4.   do if  $f_1[j-1] + a_{1,j} \leq f_2[j-1] + t_{2,j-1} + a_{1,j}$ 
5.     then  $f_1[j] \leftarrow f_1[j-1] + a_{1,j}$ 
6.        $l_1[j] \leftarrow 1$ 
7.     else  $f_1[j] \leftarrow f_2[j-1] + t_{2,j-1} + a_{1,j}$ 
8.        $l_1[j] \leftarrow 2$ 
    } Compute the values of  $f_1[j]$  and  $l_1[j]$ 
9.   if  $f_2[j-1] + a_{2,j} \leq f_1[j-1] + t_{1,j-1} + a_{2,j}$ 
10.    then  $f_2[j] \leftarrow f_2[j-1] + a_{2,j}$ 
11.       $l_2[j] \leftarrow 2$ 
12.    else  $f_2[j] \leftarrow f_1[j-1] + t_{1,j-1} + a_{2,j}$ 
    } Compute the values of  $f_2[j]$  and  $l_2[j]$ 
13.     $l[j] \leftarrow 1$ 

```

FASTEST-WAY(a, t, e, x, n) (cont.)

14. **if** $f_1[n] + x_1 \leq f_2[n] + x_2$

15. **then** $f^* = f_1[n] + x_1$

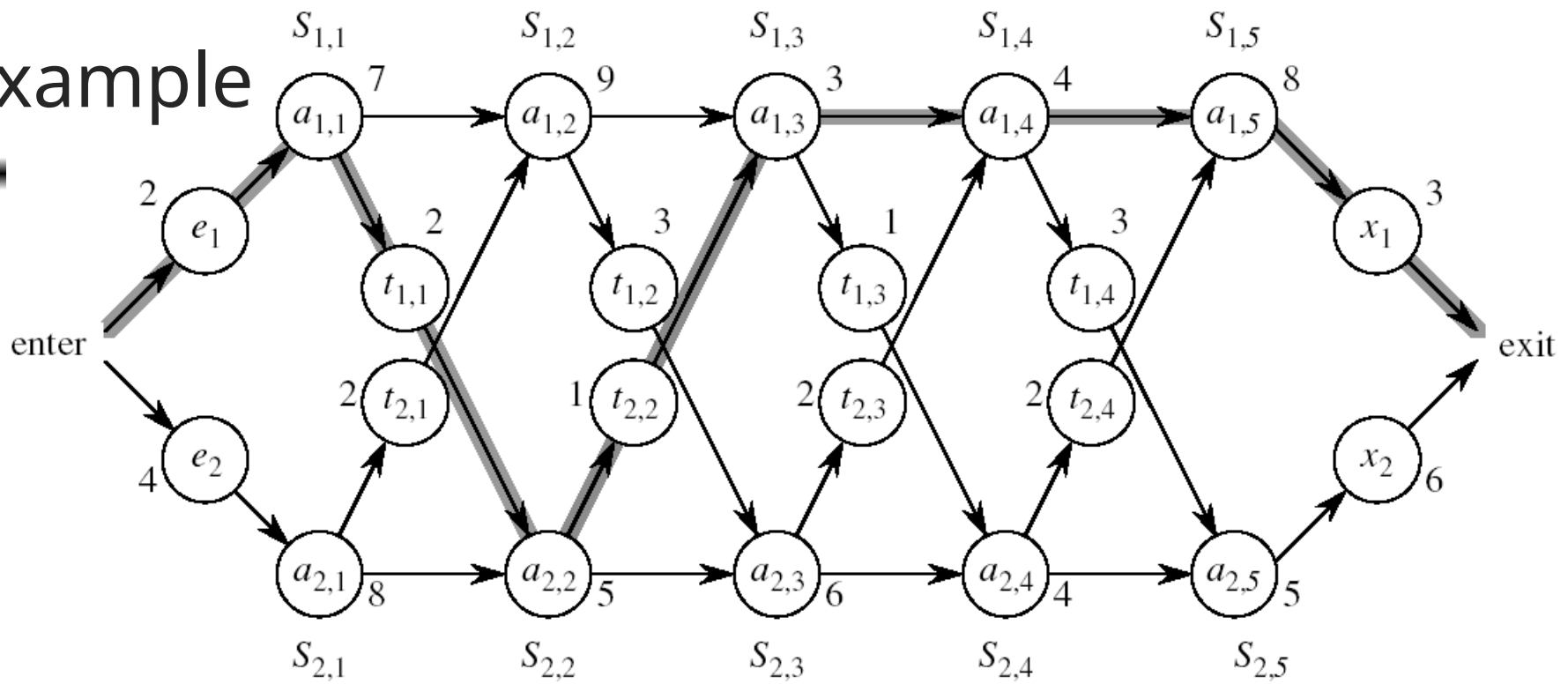
16. $l^* = 1$

17. **else** $f^* = f_2[n] + x_2$

18. $l^* = 2$

} Compute the values of
the fastest time through the
entire factory

Example



$$f_1[j] = \begin{cases} e_1 + a_{1,1}, & \text{if } j = 1 \\ \min(f_1[j-1] + a_{1,j}, f_2[j-1] + t_{2,j-1} + a_{1,j}) & \text{if } j \geq 2 \end{cases}$$

	1	2	3	4	5
$f_1[j]$	9	18 ^[1]	20 ^[2]	24 ^[1]	32 ^[1]
$f_2[j]$	12	16 ^[1]	22 ^[2]	25 ^[1]	30 ^[2]

$$f^* = 35^{[1]}$$

4. Construct an Optimal Solution

Alg.: PRINT-STATIONS(l, n)

$i \leftarrow l^*$

print "line " i ", station " n

for $j \leftarrow n$ **downto** 2

do $i \leftarrow l_i[j]$

print "line " i ", station " $j - 1$

line 1, station 5

line 1, station 4

line 1, station 3

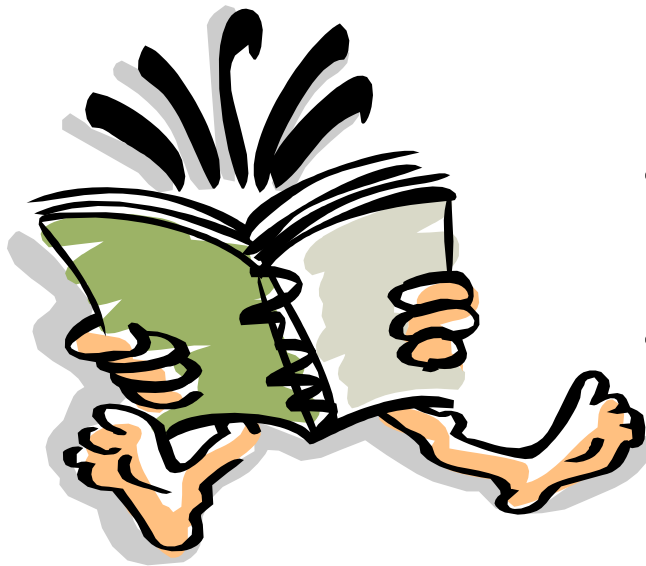
line 2, station 2

line 1, station 1

	1	2	3	4	5
$f_1[j]$ $l^1[j]$	9	18 ^[1]	20 ^[2]	24 ^[1]	32 ^[1]
$f_2[j]$ $l^2[j]$	12	16 ^[1]	22 ^[2]	25 ^[1]	30 ^[2]

$l^* = 1$

Readings



- For this lecture
 - Chapter 14
- Coming next
 - Chapter 14