

Analysis of Algorithms

CS 477/677

Instructor: Monica Nicolescu

Lecture 24

Lemma

A directed graph is **acyclic** \iff a DFS on G yields no back edges.

Proof:

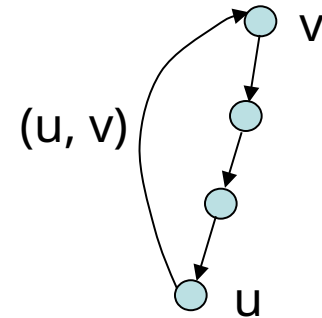
" \Rightarrow ": acyclic \Rightarrow no back edge

- Assume **back edge** \Rightarrow prove **cycle**
- Assume there is a back edge (u, v)

$\Rightarrow v$ is an ancestor of u

\Rightarrow there is a path from v to u in G ($v \sqsubseteq u$)

$\Rightarrow v \sqsubseteq u$ + the back edge (u, v) yield a cycle



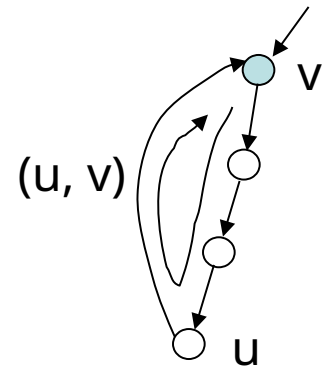
Lemma

A directed graph is **acyclic** \iff a DFS on G yields no back edges.

Proof:

" \Leftarrow ": no back edge \Rightarrow acyclic

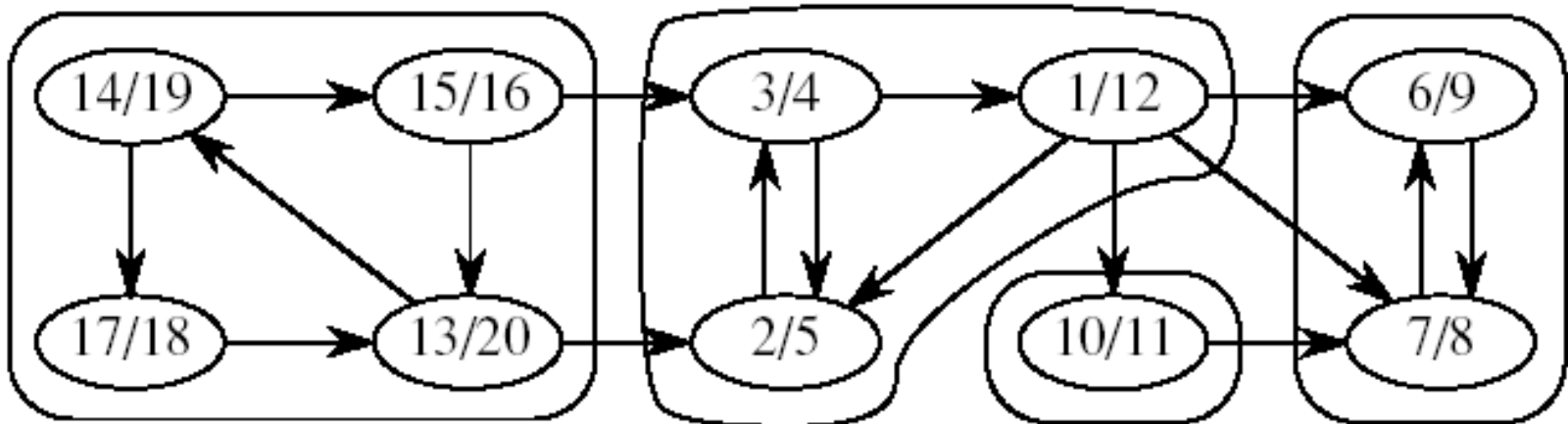
- Assume **cycle** \Rightarrow prove **back edge**
 - Suppose G contains cycle c
 - Let v be the first vertex discovered in c , and (u, v) be the preceding edge in c
 - At time $d[v]$, vertices of c form a white path $v \sqsubseteq u$
 - u is descendant of v in depth-first forest (by white-path theorem)
- $\Rightarrow (u, v)$ is a back edge



Strongly Connected Components

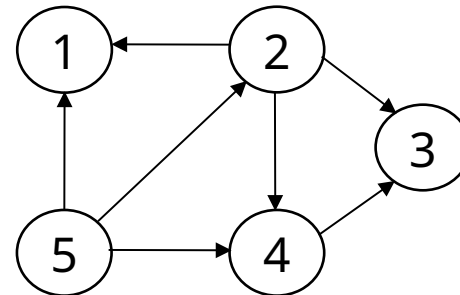
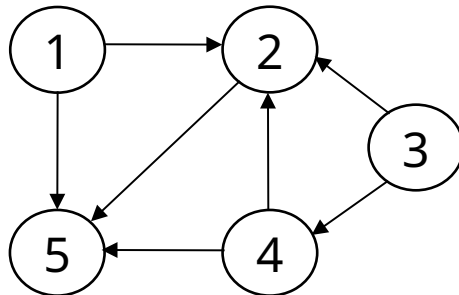
Given directed graph $G = (V, E)$:

A **strongly connected component (SCC)** of G is a maximal set of vertices $C \subseteq V$ such that for every pair of vertices $u, v \in C$, we have both $u \rightarrow v$ and $v \rightarrow u$.



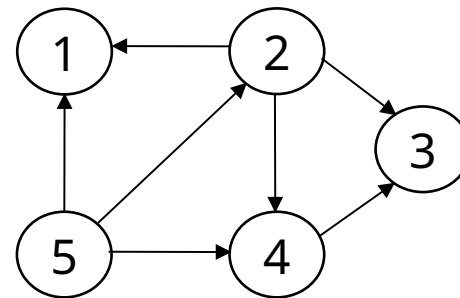
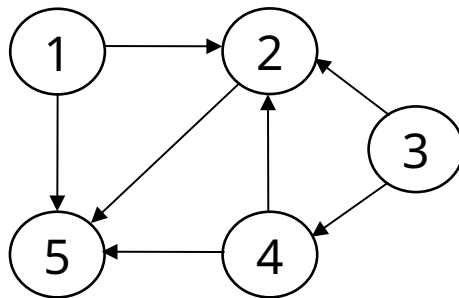
The Transpose of a Graph

- $G^T = \text{transpose of } G$
 - G^T is G with all edges reversed
 - $G^T = (V, E^T)$, $E^T = \{(u, v) : (v, u) \in E\}$
- If using adjacency lists: we can create G^T in $\Theta(|V| + |E|)$ time



Finding the SCC

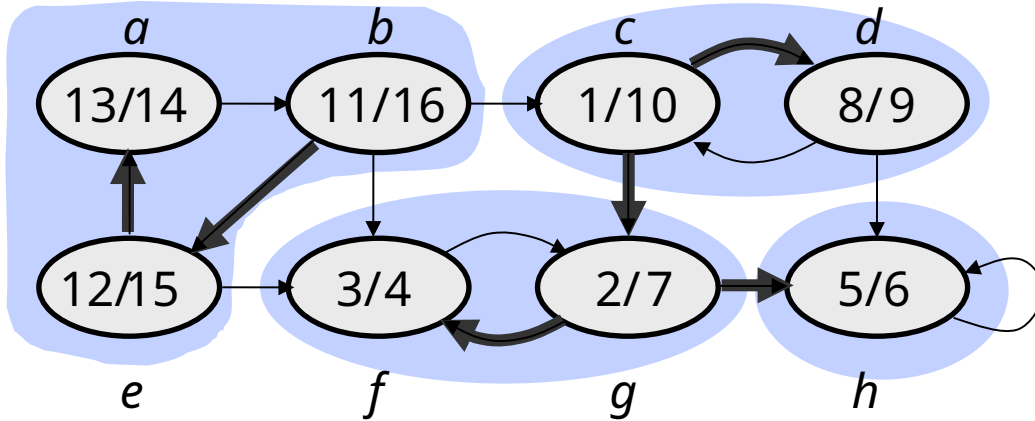
- **Observation:** G and G^T have the same SCC's
 - u and v are reachable from each other in $G \iff$ they are reachable from each other in G^T
- Idea for computing the SCC of a graph $G = (V, E)$:
 - Make two depth first searches: one on G and one on G^T



STRONGLY-CONNECTED-COMPONENTS(G)

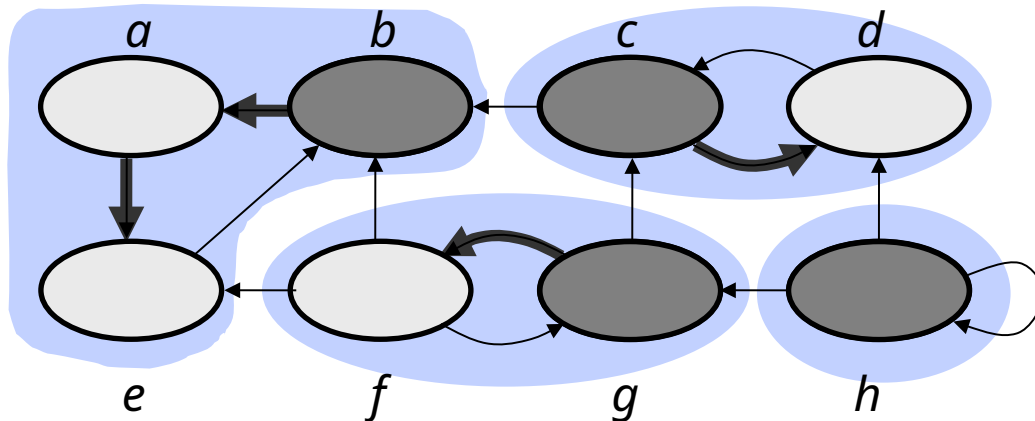
1. call DFS(G) to compute finishing times $f[u]$ for each vertex u
2. compute G^T
3. call DFS(G^T), but in the main loop of DFS, consider vertices in order of decreasing $f[u]$ (as computed in first DFS)
4. output the vertices in each tree of the depth-first forest formed in second DFS as a separate SCC

Example



DFS on the initial graph G

b	e	a	c	d	g	h	f
1	1	1	1	9	7	6	4
6	5	4	0				

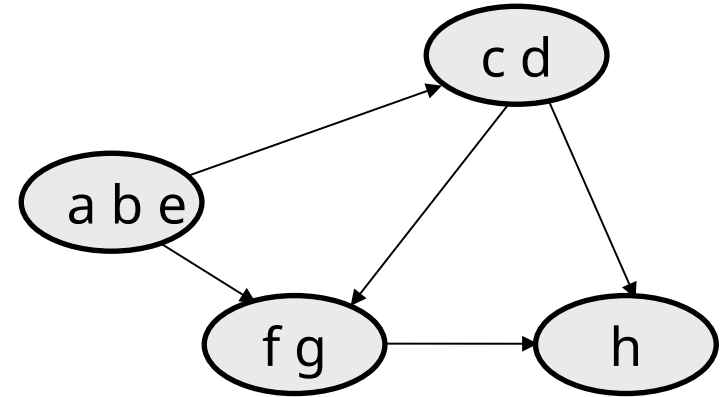
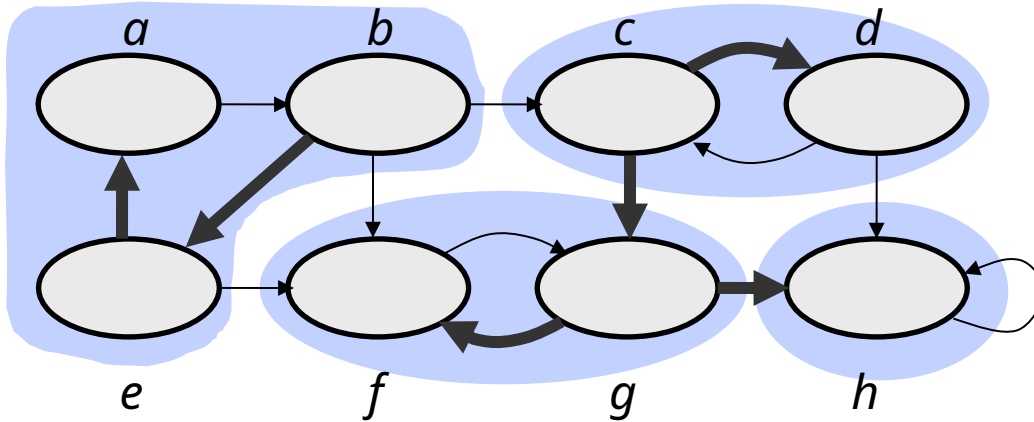


DFS on G^T :

- start at b: visit a, e
- start at c: visit d
- start at g: visit f
- start at h

Strongly connected components: $C_1 = \{a, b, e\}$, $C_2 = \{c, d\}$, $C_3 = \{f, g\}$, $C_4 = \{h\}$

Component Graph



- The **component graph** $G^{SCC} = (V^{SCC}, E^{SCC})$:
 - $V^{SCC} = \{v_1, v_2, \dots, v_k\}$, where v_i corresponds to each strongly connected component C_i
 - There is an edge $(v_i, v_j) \in E^{SCC}$ if G contains a directed edge (x, y) for some $x \in C_i$ and $y \in C_j$
- The component graph is a DAG

Lemma 1

Let C and C' be distinct SCC's in G

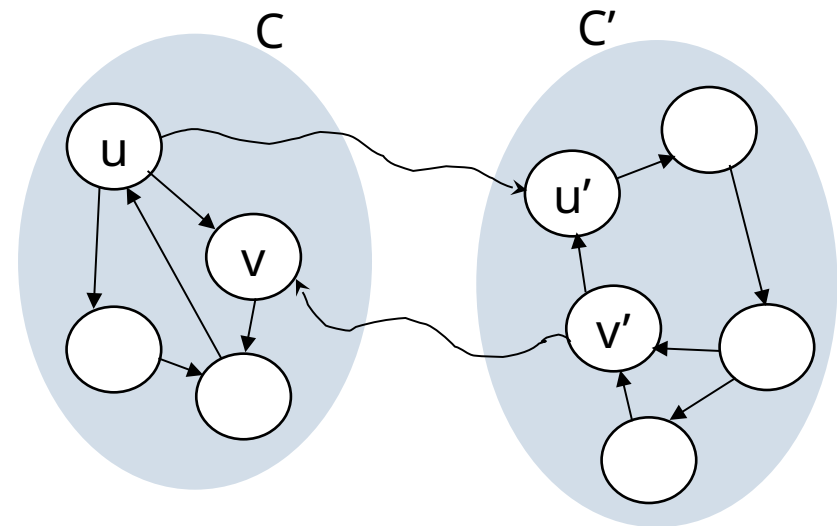
Let $u, v \in C$, and $u', v' \in C'$

Suppose there is a path $u \rightarrow u'$ in G

Then there cannot also be a path $v' \rightarrow v$ in G .

Proof

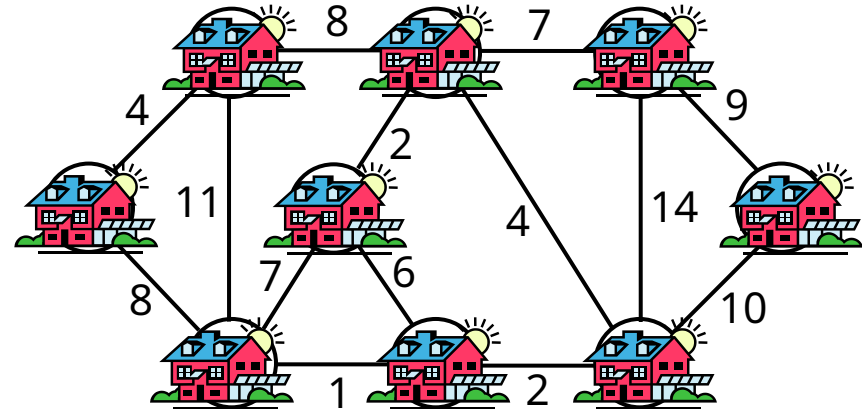
- Suppose there is a path $v' \rightarrow v$
- There exists $u \rightarrow u' \rightarrow v'$
- There exists $v' \rightarrow v \rightarrow u$
- u and v' are reachable from each other, so they are not in separate SCC's: contradiction!



Minimum Spanning Trees

Problem

- A town has a set of houses and a set of roads
- A road connects 2 and only 2 houses
- A road connecting houses u and v has a repair cost $w(u, v)$



Goal: Repair enough (and no more) roads such that:

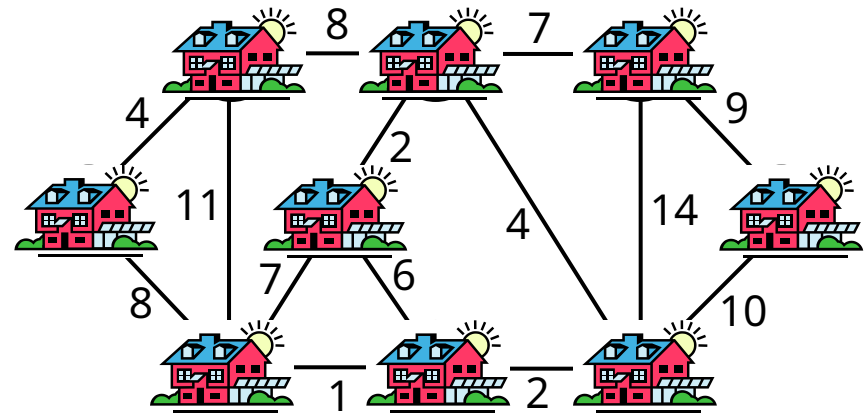
1. Everyone stays connected: can reach every house from all other houses, and
2. Total repair cost is minimum

Minimum Spanning Trees

- A connected, undirected graph:
 - Vertices = houses, Edges = roads
- A **weight** $w(u, v)$ on each edge $(u, v) \in E$

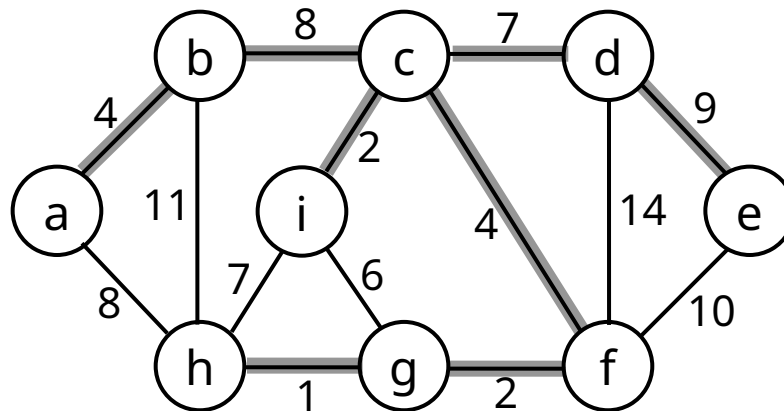
Find $T \subseteq E$ such that:

1. T connects all vertices
2. $w(T) = \sum_{(u,v) \in T} w(u, v)$ is minimized



Minimum Spanning Trees

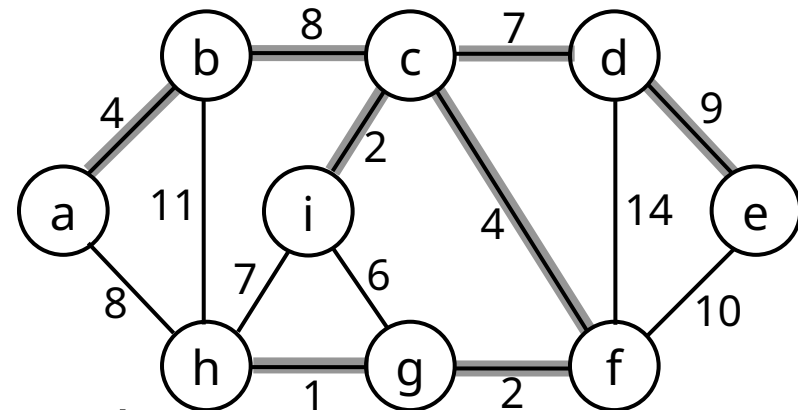
- T forms a tree = **spanning tree**
- A spanning tree whose weight is minimum over all spanning trees is called a ***minimum spanning tree***, or ***MST***.



Properties of MSTs

- Minimum spanning trees are not unique
 - Can replace (b, c) with (a, h) to obtain a different spanning tree with the same cost

- MST have no cycles
 - We can take out an edge of a cycle, and still have all vertices connected while reducing the cost



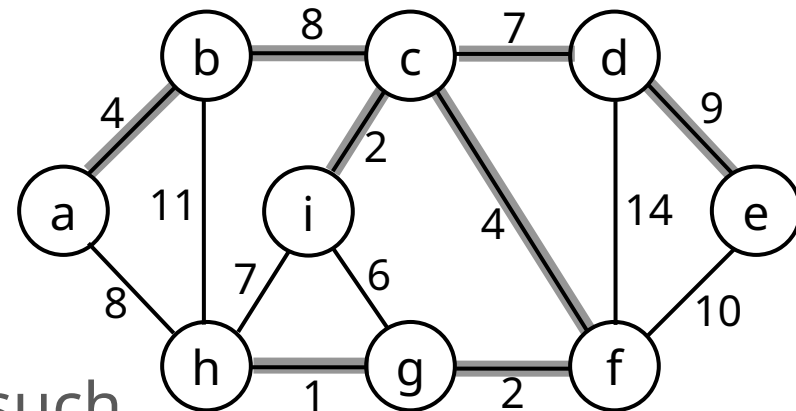
- # of edges in a MST:
 - $|V| - 1$

Growing a MST

Minimum-spanning-tree problem: find a MST for a connected, undirected graph, with a weight function associated with its edges

A generic solution:

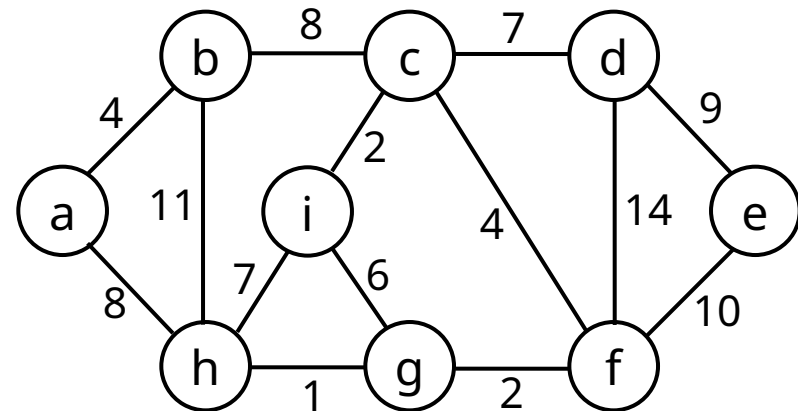
- Build a set A of edges (initially empty)
- Incrementally add edges to A such that they would belong to a MST
- An edge (u, v) is **safe** for A if and only if $A \cup \{(u, v)\}$ is also a subset of some MST – **greedy choice property**



We will add only safe edges

GENERIC-MST

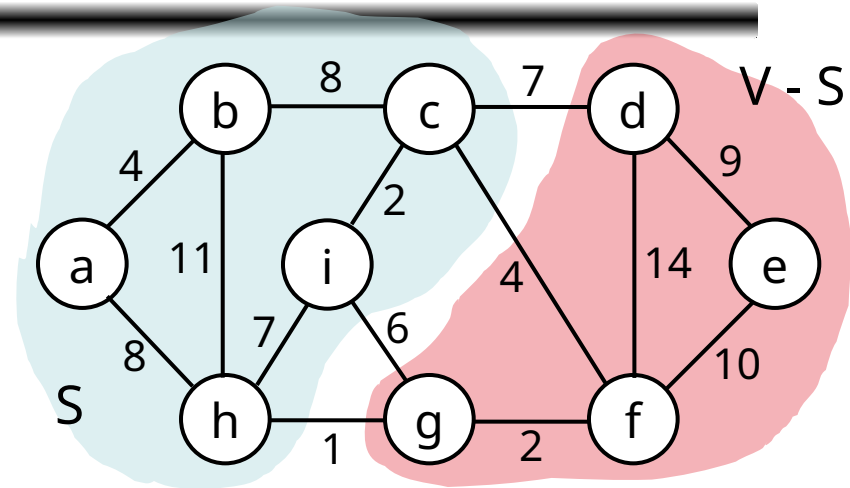
1. $A \leftarrow \emptyset$
2. **while** A is not a spanning tree
3. **do** find an edge (u, v) that is safe for A
4. $A \leftarrow A \cup \{(u, v)\}$
5. **return** A



- How do we find safe edges?

Finding Safe Edges

- Let's look at edge (h, g)
 - Is it safe for A initially?
- Later on:



- Let $S \subset V$ be any set of vertices that includes h but not g (so that g is in $V - S$)
- In any MST, there has to be one edge (at least) that connects S with $V - S$
- Why not choose the edge with minimum weight (h, g) ?

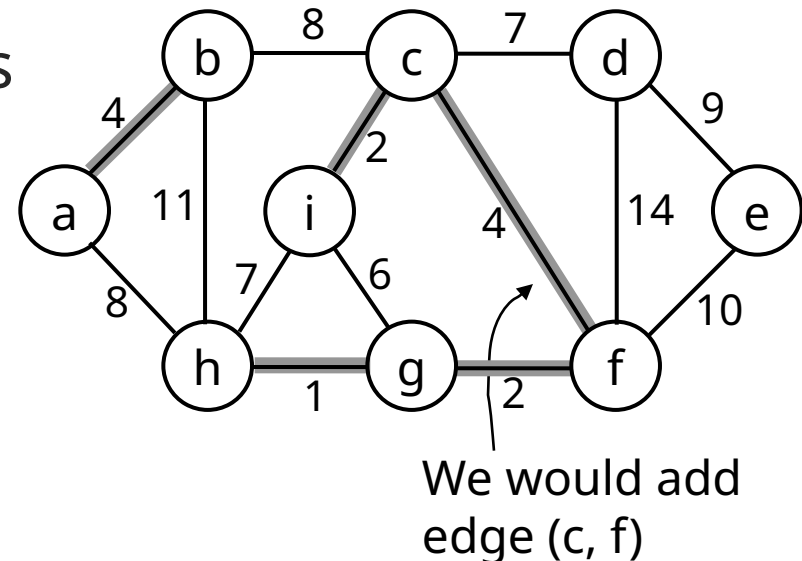
Discussion

In GENERIC-MST:

- A is a forest containing connected components
 - Initially, each component is a single vertex
- Any safe edge merges two of these components into one
 - Each component is a tree
- Since an MST has exactly $|V| - 1$ edges: after iterating $|V| - 1$ times, we have only one component

The Algorithm of Kruskal

- Start with each vertex being its own component
- Repeatedly merge two components into one by choosing the light edge that connects them



- Scan the set of edges in monotonically increasing order by weight
- Uses a **disjoint-set** data structure to determine whether an edge connects vertices in different components

Operations on Disjoint Data Sets

- MAKE-SET(u) – creates a new set whose only member is u
- FIND-SET(u) – returns a representative element from the set that contains u
 - May be any of the elements of the set that has a particular property
 - E.g.: $S_u = \{r, s, t, u\}$, the property may be that the element is the first one alphabetically
$$\text{FIND-SET}(u) = r \quad \text{FIND-SET}(s) = r$$
 - FIND-SET has to return the same value for a given set

Operations on Disjoint Data Sets

- $\text{UNION}(u, v)$ – unites the dynamic sets that contain u and v , say S_u and S_v

– E.g.: $S_u = \{r, s, t, u\}$, $S_v = \{v, x, y\}$

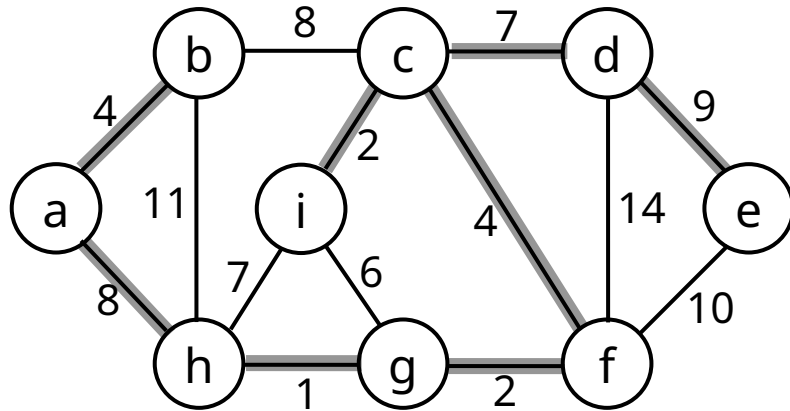
$\text{UNION}(u, v) = \{r, s, t, u, v, x, y\}$

KRUSKAL(V, E, w)

1. $A \leftarrow \emptyset$
2. **for** each vertex $v \in V$
3. **do** MAKE-SET(v)
4. sort E into increasing order by weight w
5. **for** each (u, v) taken from the sorted list
6. **do if** FIND-SET(u) \neq FIND-SET(v)
7. **then** $A \leftarrow A \cup \{(u, v)\}$
8. UNION(u, v)
9. **return** A

Running time: $O(|E| \lg |V|)$ – dependent on the implementation of the disjoint-set data structure

Example



1: (h, g) 8: (a, h), (b, c)

2: (c, i), (g, f) 9: (d, e)

4: (a, b), (c, f) 10: (e, f)

6: (i, g) 11: (b, h)

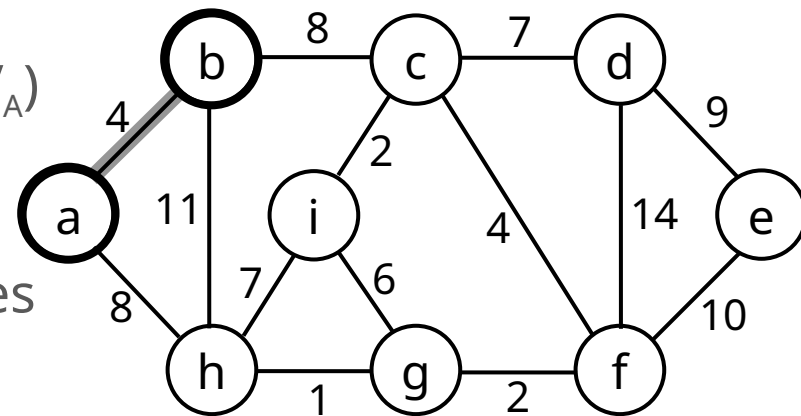
7: (c, d), (i, h) 14: (d, f)

{a}, {b}, {c}, {d}, {e}, {f}, {g}, {h}, {i}

1. Add (h, g) {g, h}, {a}, {b}, {c}, {d}, {e}, {f}, {i}
2. Add (c, i) {g, h}, {c, i}, {a}, {b}, {d}, {e}, {f}
3. Add (g, f) {g, h, f}, {c, i}, {a}, {b}, {d}, {e}
4. Add (a, b) {g, h, f}, {c, i}, {a, b}, {d}, {e}
5. Add (c, f) {g, h, f, c, i}, {a, b}, {d}, {e}
6. Ignore (i, g) {g, h, f, c, i}, {a, b}, {d}, {e}
7. Add (c, d) {g, h, f, c, i, d}, {a, b}, {e}
8. Ignore (i, h) {g, h, f, c, i, d}, {a, b}, {e}
9. Add (a, h) {g, h, f, c, i, d, a, b}, {e}
10. Ignore (b, c) {g, h, f, c, i, d, a, b}, {e}
11. Add (d, e) {g, h, f, c, i, d, a, b, e}
12. Ignore (e, f) {g, h, f, c, i, d, a, b, e}
13. Ignore (b, h) {g, h, f, c, i, d, a, b, e}
14. Ignore (d, f) {g, h, f, c, i, d, a, b, e}

The Algorithm of Prim

- The edges in set A always form a single tree
- Starts from an arbitrary “root”: $V_A = \{a\}$
- At each step:
 - Find a safe edge connecting $(V_A, V - V_A)$
 - Add this edge to A
 - Repeat until the tree spans all vertices
- Greedy strategy
 - At each step the edge added contributes the minimum amount possible to the weight of the tree



How to Find Light Edges Quickly?

Use a priority queue Q :

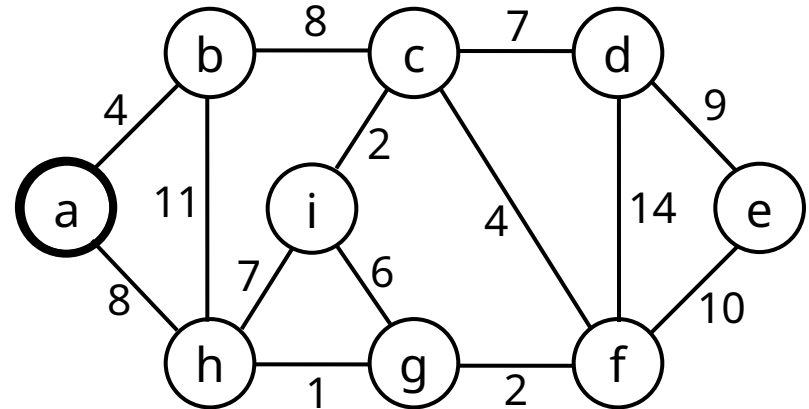
- Contains all vertices not yet included in the tree ($V - V_A$)

- $V = \{a\}$, $Q = \{b, h, c, d, e, f, g, i\}$

- With each vertex v we associate a key:

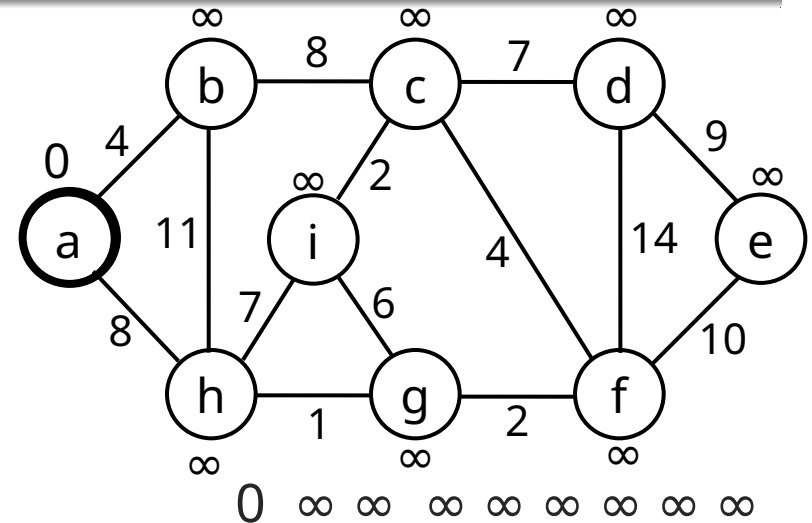
$\text{key}[v] = \text{minimum weight of any edge } (u, v)$
connecting v to a vertex in the tree

- Key of v is ∞ if v is not adjacent to any vertices in V_A
 - After adding a new node to V_A we update the weights of all the nodes adjacent to it
 - We added node $a \Rightarrow \text{key}[b] = 4, \text{key}[h] = 8$



PRIM(V, E, w, r)

1. $Q \leftarrow \emptyset$
2. **for** each $u \in V$
3. **do** $\text{key}[u] \leftarrow \infty$
4. $\pi[u] \leftarrow \text{NIL}$
5. $\text{INSERT}(Q, u)$
6. $\text{DECREASE-KEY}(Q, r, 0)$
7. **while** $Q \neq \emptyset$
8. **do** $u \leftarrow \text{EXTRACT-MIN}(Q)$
9. **for** each $v \in \text{Adj}[u]$
10. **do if** $v \in Q$ and $w(u, v) < \text{key}[v]$
11. **then** $\pi[v] \leftarrow u$
12. $\text{DECREASE-KEY}(Q, v, w(u, v))$

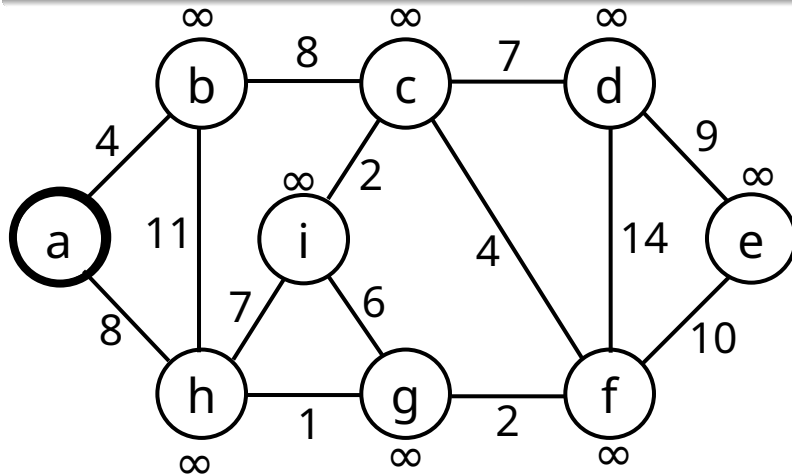


$Q = \{a, b, c, d, e, f, g, h, i\}$

$V_A = \emptyset$

$\text{Extract-MIN}(Q) \Rightarrow a$

Example

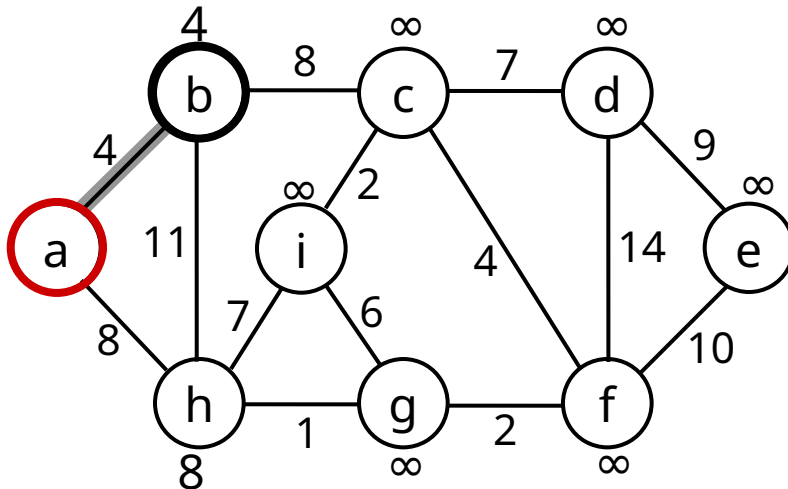


0 ∞ ∞ ∞ ∞ ∞ ∞ ∞ ∞

$Q = \{a, b, c, d, e, f, g, h, i\}$

$V_A = \emptyset$

Extract-MIN(Q) $\Rightarrow a$



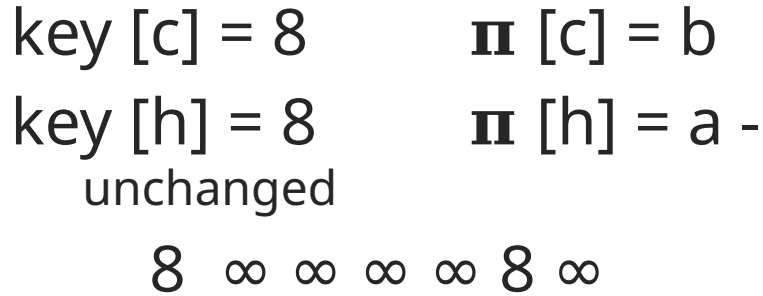
key $[b] = 4$ $\Pi[b] = a$

key $[h] = 8$ $\Pi[h] = a$

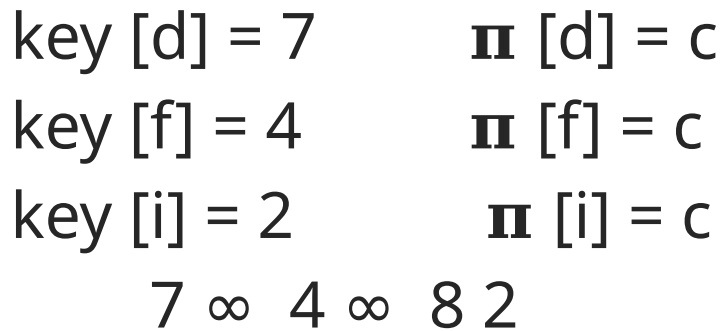
4 ∞ ∞ ∞ ∞ ∞ 8 ∞

$Q = \{b, c, d, e, f, g, h, i\}$ $V_A = \{a\}$

Extract-MIN(Q) $\Rightarrow b$

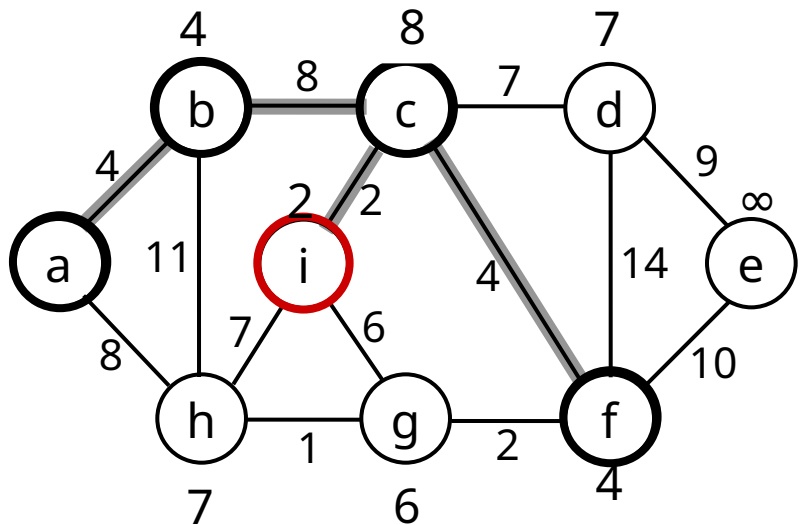


Extract-MIN(Q) \Rightarrow c



Extract-MIN(Q) \Rightarrow i

Example



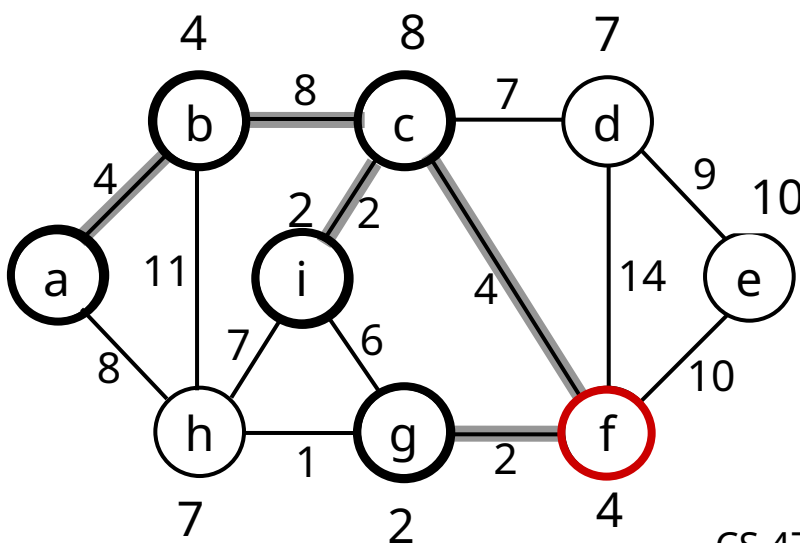
key [h] = 7 π [h] = i

key [g] = 6 π [g] = i

7 ∞ 4 6 7

$Q = \{d, e, f, g, h\}$ $V_A = \{a, b, c, i\}$

Extract-MIN(Q) \Rightarrow f



key [g] = 2 π [g] = f

key [d] = 7 π [d] = c

unchanged

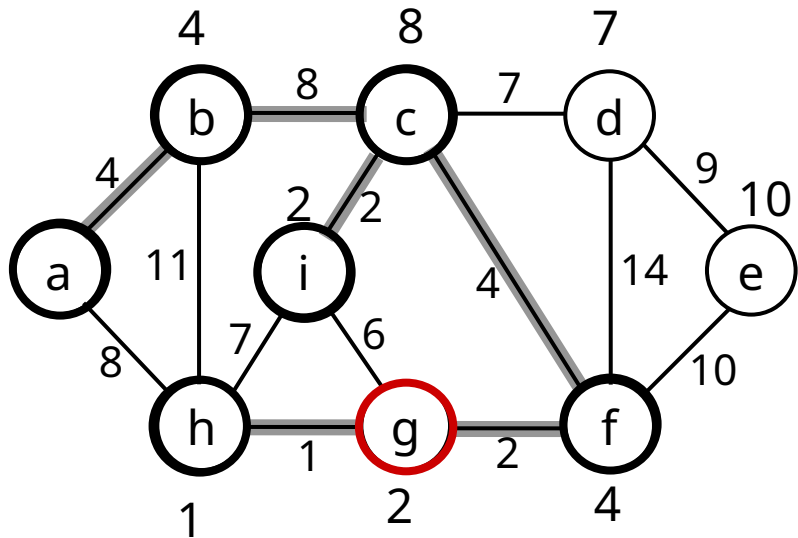
key [e] = 10 π [e] = f

7 10 2 7

$Q = \{d, e, g, h\}$ $V_A = \{a, b, c, i, f\}$

Extract-MIN(Q) \Rightarrow g

Example

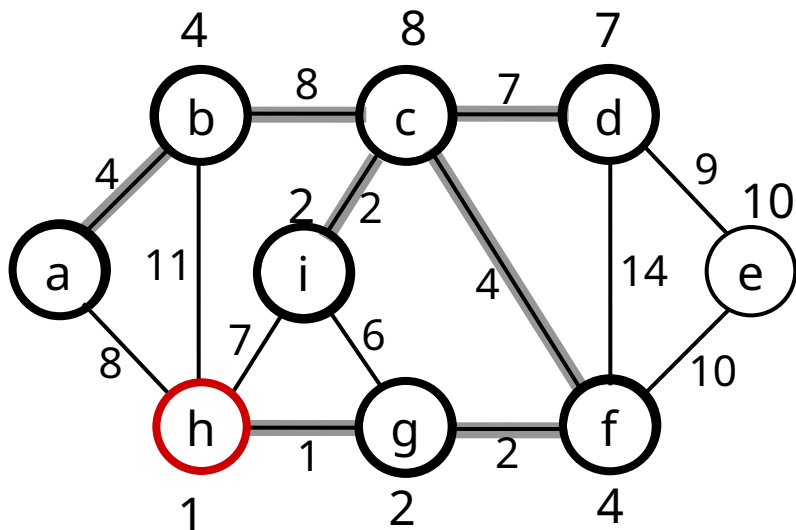


key [h] = 1 Π [h] = g

7 10 1

$Q = \{d, e, h\}$ $V_A = \{a, b, c, i, f, g\}$

Extract-MIN(Q) \Rightarrow h

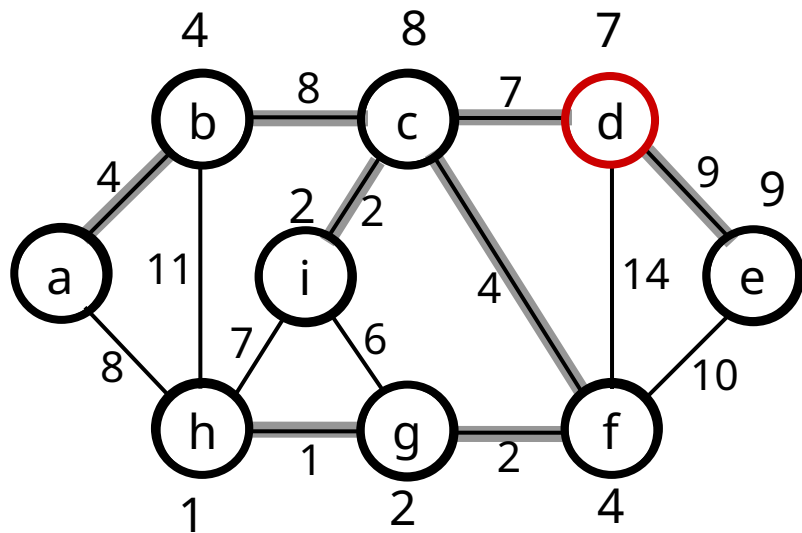


7 10

$Q = \{d, e\}$ $V_A = \{a, b, c, i, f, g, h\}$

Extract-MIN(Q) \Rightarrow d

Example



key [e] = 9 Π [e] = d
9

$Q = \{e\}$ $V_A = \{a, b, c, i, f, g, h, d\}$

Extract-MIN(Q) $\Rightarrow e$

$Q = \emptyset$ $V_A = \{a, b, c, i, f, g, h, d, e\}$

PRIM(V, E, w, r)

```

1.  Q ← ∅
2.  for each u ∈ V
3.      do key[u] ← ∞
4.      π[u] ← NIL
5.      INSERT(Q, u)
6.  DECREASE-KEY(Q, r, 0)      ► key[r] ← 0
7.  while Q ≠ ∅
8.      do u ← EXTRACT-MIN(Q)
9.          for each v ∈ Adj[u]
10.             do if v ∈ Q and w(u, v) < key[v]
11.                 then π[v] ← u
12.                 DECREASE-KEY(Q, v, w(u, v))

```

Total time: $O(V \lg V + E \lg V) = O(E \lg V)$

$O(V)$ if Q is implemented as a min-heap

Executed V times

Takes $O(\lg V)$

Min-heap operations: $O(V \lg V)$

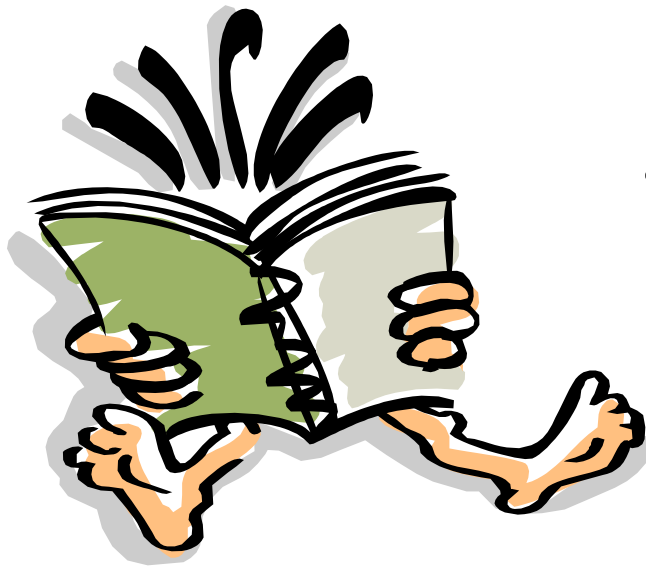
Executed $O(E)$ times

Constant

Takes $O(\lg V)$

$O(E \lg V)$

Readings



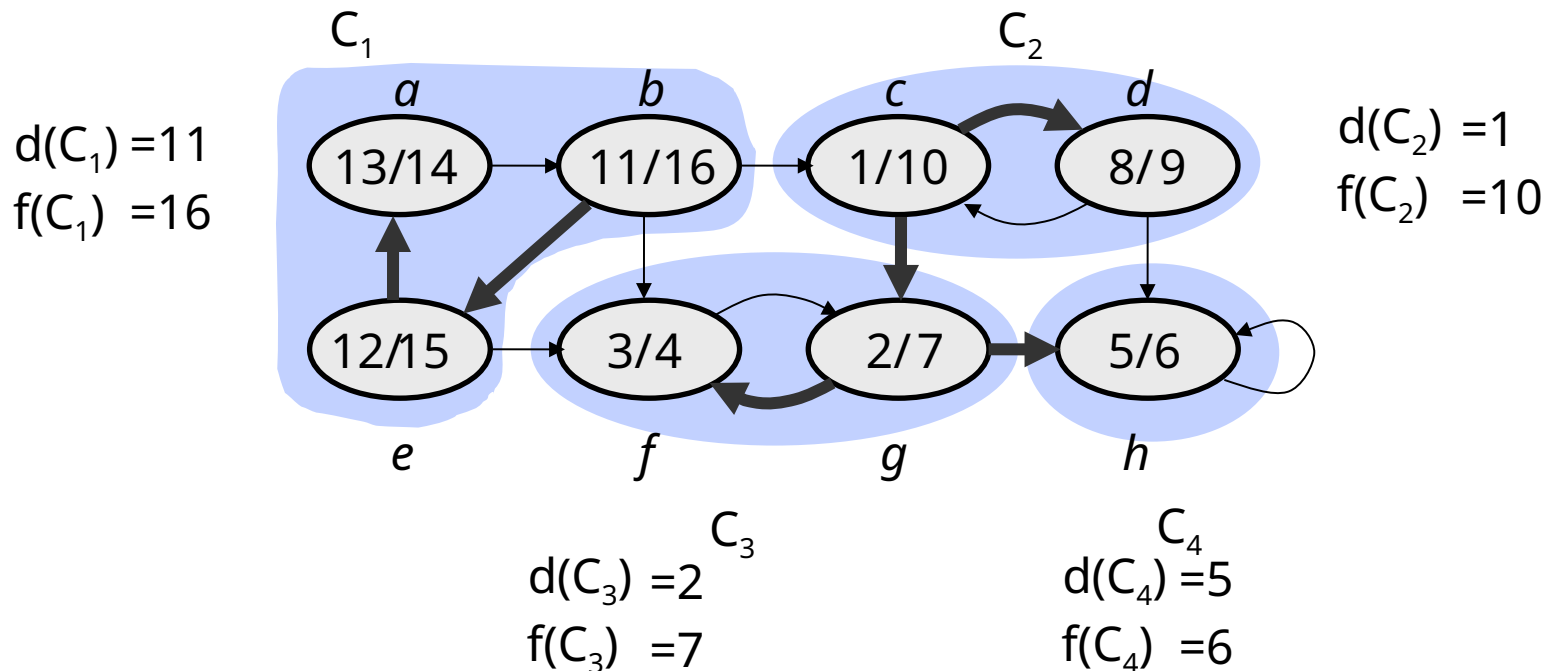
- Chapters 25, 31

optional

ADDITIONAL SLIDES

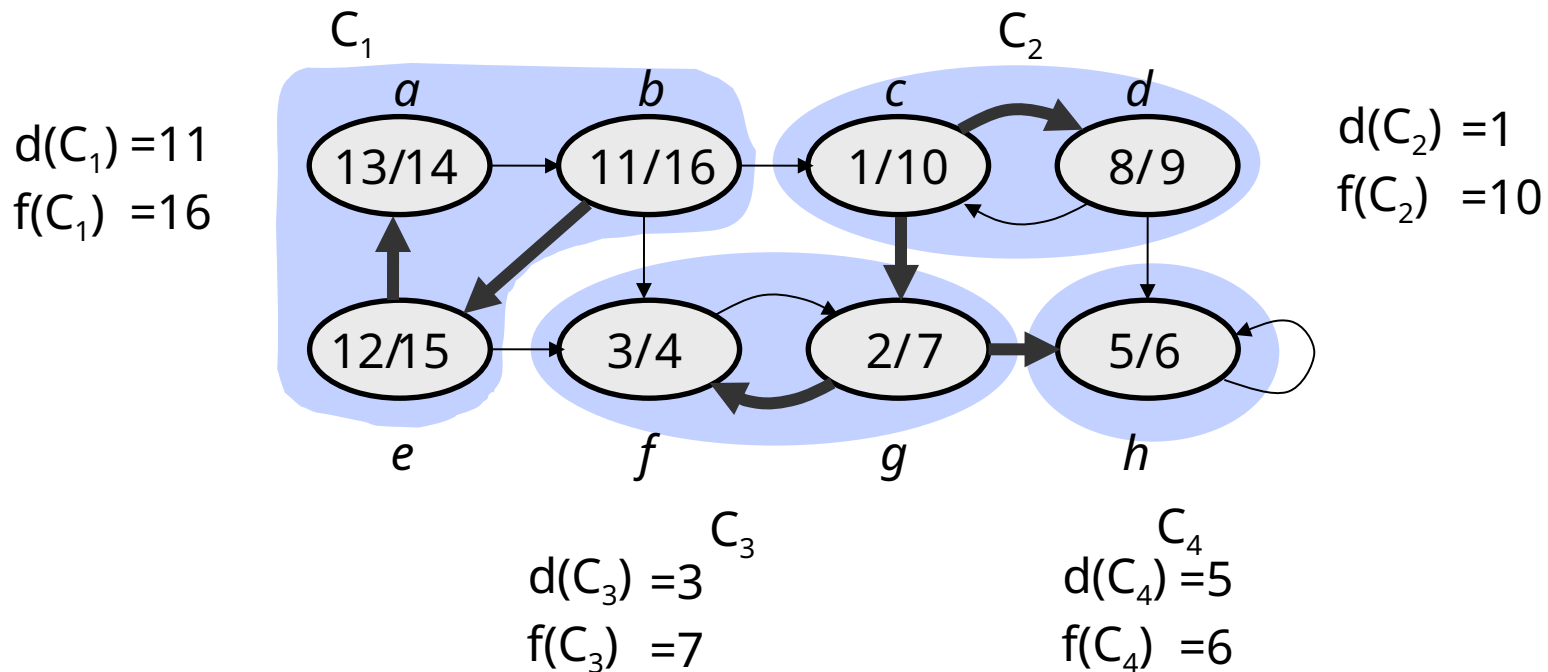
Notations

- Extend notation for d (starting time) and f (finishing time) to sets of vertices $U \subseteq V$:
 - $d(U) = \min_{u \in U} \{ d[u] \}$ (earliest discovery time)
 - $f(U) = \max_{u \in U} \{ f[u] \}$ (latest finishing time)



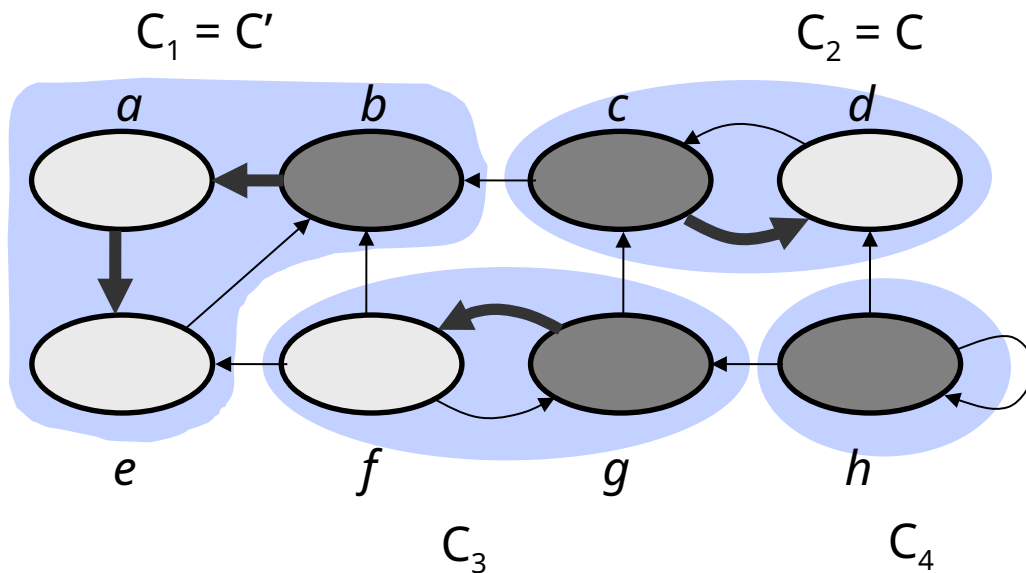
Lemma 2

- Let C and C' be distinct SCCs in a directed graph $G = (V, E)$. If there is an edge $(u, v) \in E$, where $u \in C$ and $v \in C'$ then $f(C) > f(C')$.
- Consider C_1 and C_2 , connected by edge (b, c)



Corollary

- Let C and C' be distinct SCCs in a directed graph $G = (V, E)$. If there is an edge $(u, v) \in E^T$, where $u \in C$ and $v \in C'$ then $f(C) < f(C')$.
- Consider C_2 and C_1 , connected by edge (c, b)

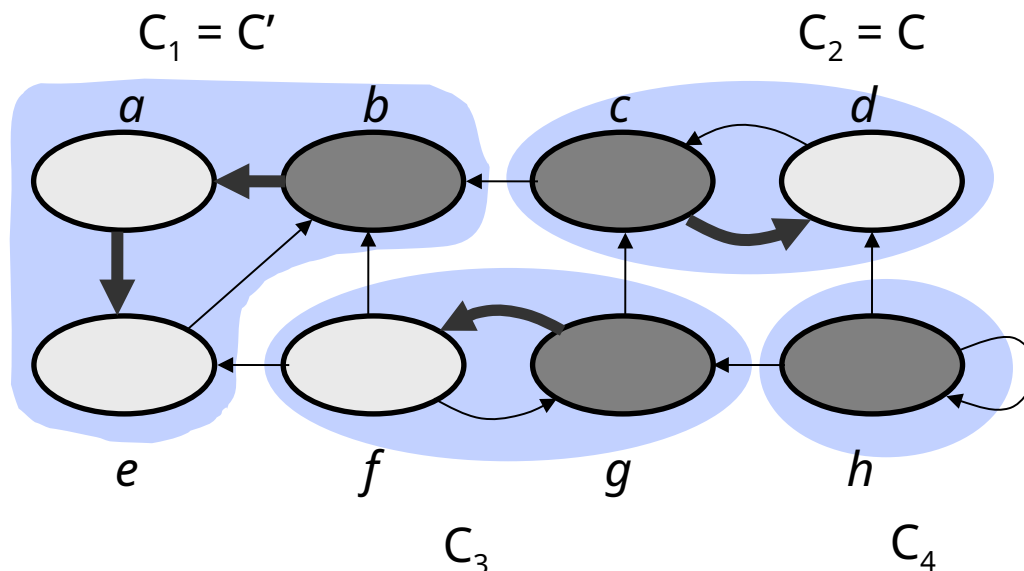


- Since $(c, b) \in E^T$
 $\Rightarrow (b, c) \in E$
- From previous lemma:
 $f(C_1) > f(C_2)$
 $f(C') > f(C)$

Discussion

$$f(C) < f(C')$$

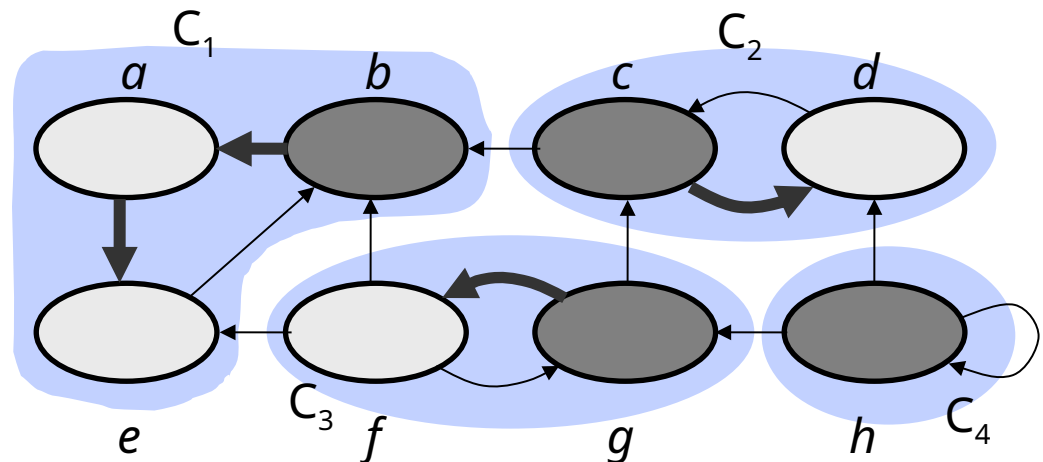
- Each edge in G^T that goes between different components goes from a component with an earlier finish time (in the DFS) to one with a later finish time



Why does SCC Work?

- When we do the second DFS, on G^T , we start with a component C such that $f(C)$ is maximum (b , in our case)
 - We start from b and visit all vertices in C_1
 - From corollary: $f(C) > f(C')$ for all $C \neq C' \Rightarrow$ there are no edges from C to any other SCCs in G^T
- \Rightarrow DFS will visit only vertices in C_1
- \Rightarrow The depth-first tree rooted at b contains exactly the vertices of C_1

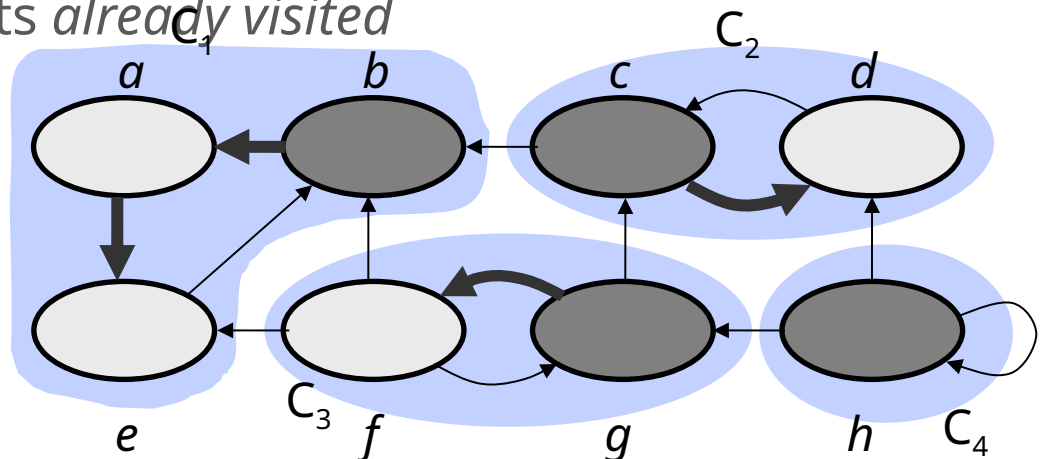
b	e	a	c	d	g	h	f
1	1	1	1	9	7	6	4
6	5	4	0				



Why does SCC Work? (cont.)

- The next root chosen in the second DFS is in SCC C_2 such that $f(C)$ is maximum over all SCC's other than C_1
 - DFS visits all vertices in C_2
 - the only edges out of C_2 go to C_1 , which we already visited
- ⇒ The only tree edges will be to vertices in C_2
- Each time we choose a new root it can reach only:
 - vertices in its own component
 - vertices in components *already visited*

b	e	a	c	d	g	h	f
1	1	1	1	9	7	6	4
6	5	4	0				



Lemma 1

Let C and C' be distinct SCC's in G

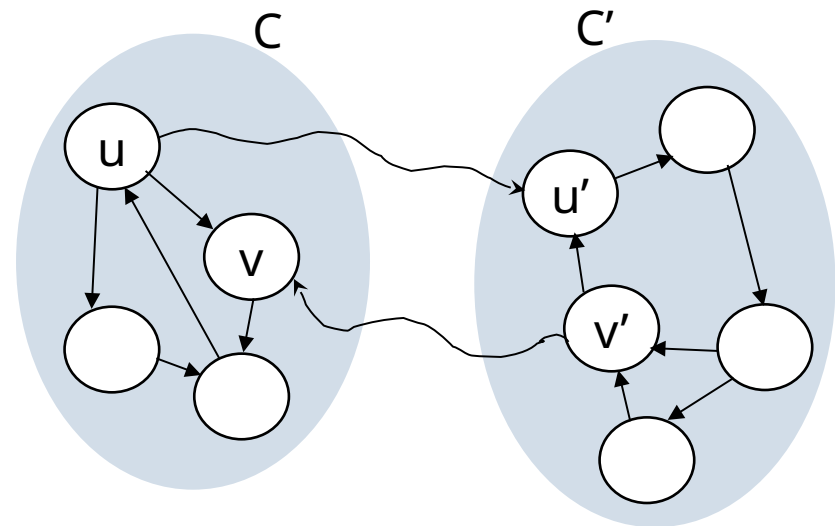
Let $u, v \in C$, and $u', v' \in C'$

Suppose there is a path $u \rightarrow u'$ in G

Then there cannot also be a path $v' \rightarrow v$ in G .

Proof

- Suppose there is a path $v' \rightarrow v$
- There exists $u \rightarrow u' \rightarrow v'$
- There exists $v' \rightarrow v \rightarrow u$
- u and v' are reachable from each other, so they are not in separate SCC's: contradiction!



Definitions

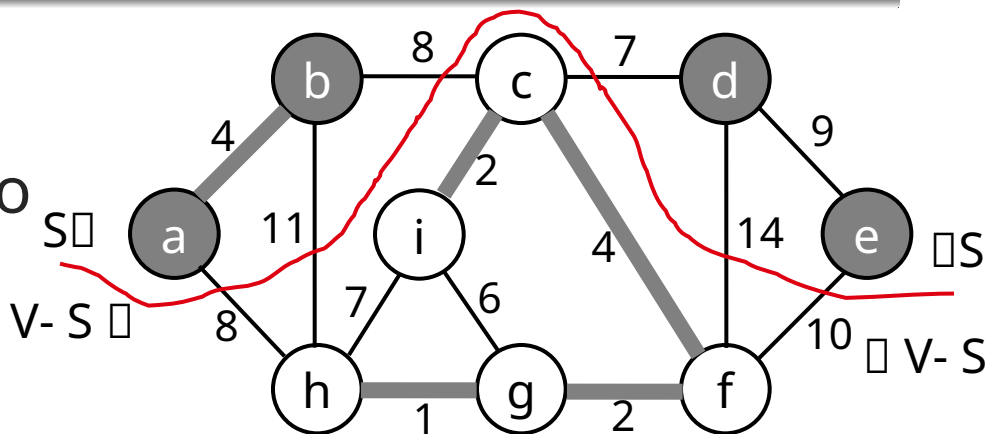
- A **cut** $(S, V - S)$

is a partition of vertices into disjoint sets S and $V - S$

- An edge **crosses** the cut

$(S, V - S)$ if one endpoint is in S and the other in $V - S$

- A cut **respects** a set A of edges \iff no edge in A crosses the cut
- An edge is a **light edge** crossing a cut \iff its weight is minimum over all edges crossing the cut
 - For a given cut, there can be several light edges crossing it

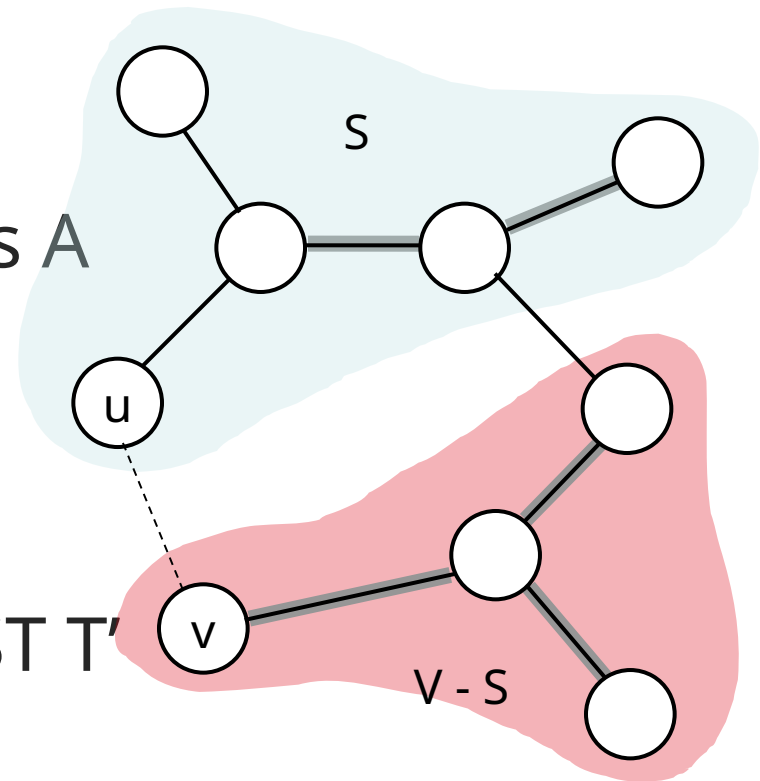


Theorem

- Let A be a subset of some MST, $(S, V - S)$ be a **cut** that respects A , and (u, v) be a **minimum weight edge** crossing $(S, V - S)$. Then (u, v) is **safe for A** .

Proof:

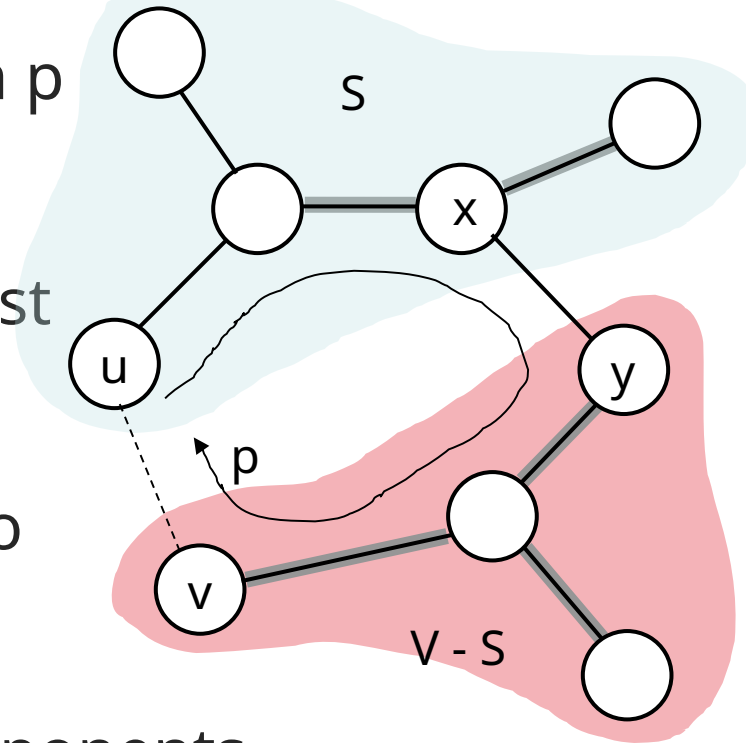
- Let T be a MST that includes A
 - Edges in A are shaded
- Assume T does not include the edge (u, v)
- Idea:** construct another MST T' that includes $A \cup \{(u, v)\}$



Theorem – Proof

- T contains a unique path p between u and v
- (u, v) forms a cycle with edges on p
- (u, v) crosses the cut \Rightarrow path p must cross the cut $(S, V - S)$ at least once: let (x, y) be that edge
- Let's remove $(x, y) \Rightarrow$ breaks T into two components.
- Adding (u, v) reconnects the components

$$T' = T - \{(x, y)\} \cup \{(u, v)\}$$

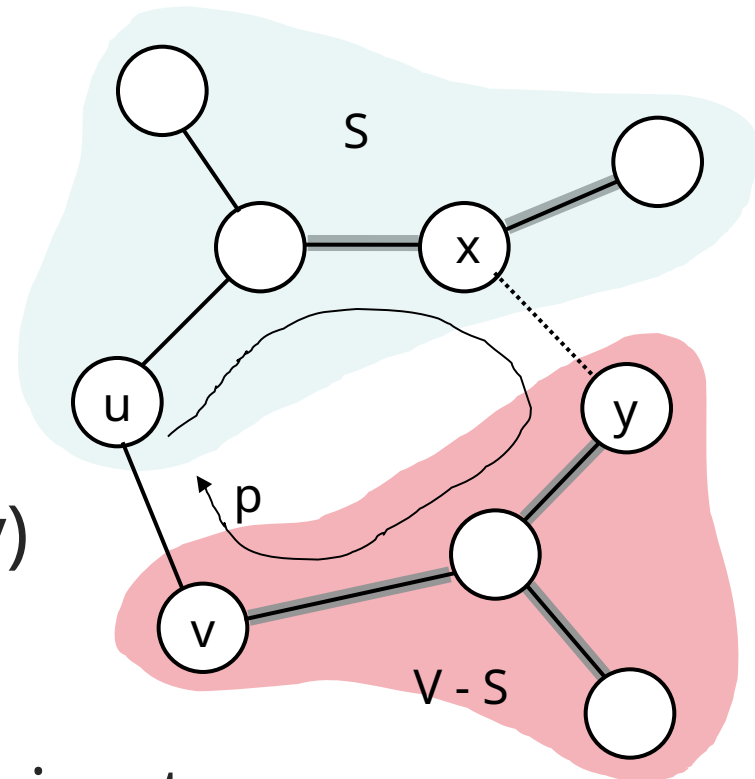


Theorem – Proof (cont.)

$$T' = T - \{(x, y)\} \cup \{(u, v)\}$$

Have to show that T' is a MST:

- (u, v) is a light edge
 $\Rightarrow w(u, v) \leq w(x, y)$
- $w(T') = w(T) - w(x, y) + w(u, v) \leq w(T)$
- Since T is a minimum spanning tree:
 $w(T) \leq w(T') \Rightarrow T'$ must be an MST as well



Theorem – Proof (cont.)

Need to show that (u, v) is safe for A :

i.e., (u, v) can be a part of a MST

- $A \subseteq T$ and $(x, y) \notin A \Rightarrow A \subseteq T'$
- $A \cup \{(u, v)\} \subseteq T'$
- Since T' is an MST

$\Rightarrow (u, v)$ is safe for A

